

# Optimal Transport Metrics

**Cambridge MLG Reading Group**

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# Why Optimal Transport?

- The natural geometry for **probability measures** supported on a **metric space**
- **Shortest path principle**
  - OT generalises this: one item  $\rightarrow$  groups of items
- Borrows key geometric properties of underlying “ground” space on which distributions are defined
  - Euclidean metric  $\rightarrow$  interpolation, barycenters, etc  $\rightarrow$  Wasserstein space
- Provides a metric (or discrepancy measure) for probability measures with **non-overlapping support**

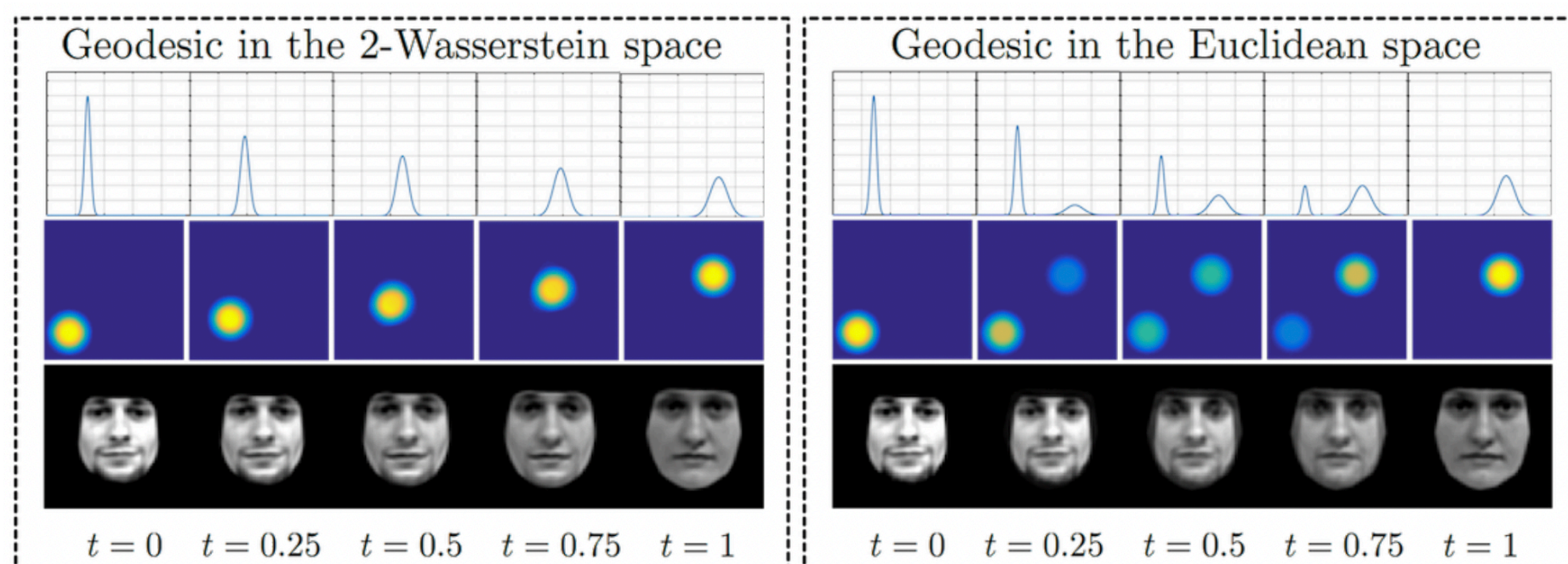


Image credit: [Kolouri et al. 2017]

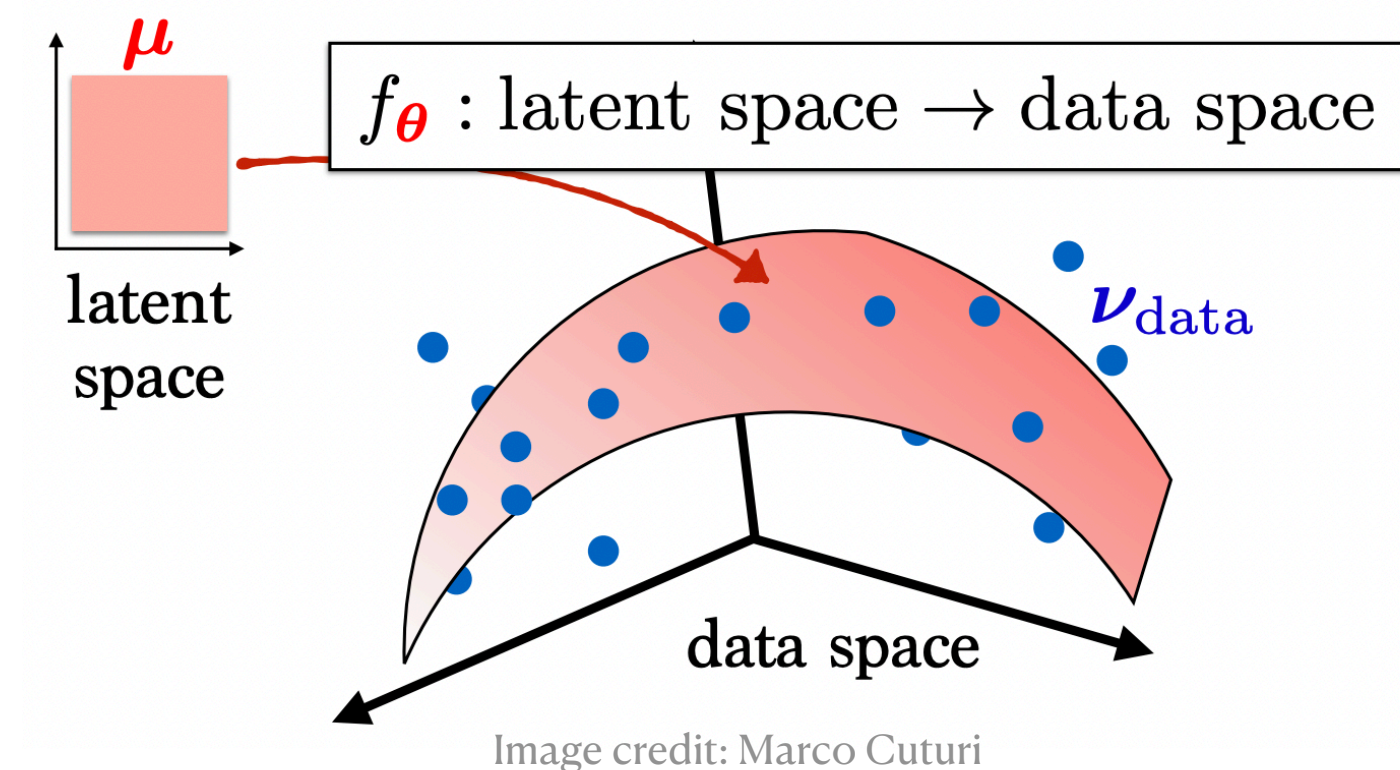


Image credit: Marco Cuturi

# In this talk

## I. Mathematical Formulation of Optimal Transport Theory

Wasserstein Distances

Computational and Statistical Issues

## II. Approximate/Regularised OT

Sliced Wasserstein Distances

Sinkhorn Divergences

## III. Applications of OT in Machine Learning

## IV. Extensions of OT

Unbalanced OT

OT on separate metrics

# **Mathematical Preliminaries**

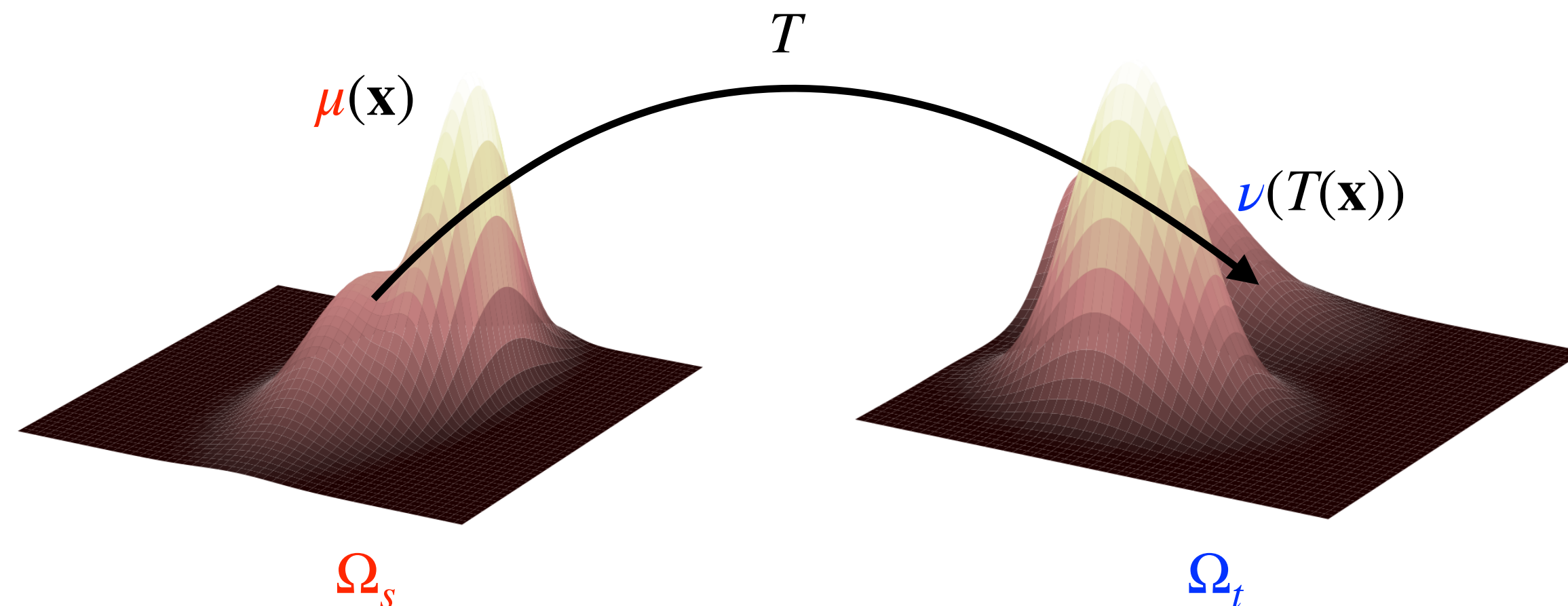
# Monge Problem

- [Monge, 1781] How does one move one pile of dirt to another while minimising effort?
- Probability measures  $\mu \in P(\Omega_s)$ ,  $\nu \in P(\Omega_t)$ , on metric spaces, and a cost function  $c : \Omega_s \times \Omega_t \rightarrow \mathbb{R}^+$
- Push-forward operator  $T\#$  transfers measures from one space  $\Omega_s$  to another  $\Omega_t$

$$\nu(A) = \mu(T^{-1}(A)), \forall \text{Borel subsets } A \in \Omega_t \quad (\text{conservation of mass})$$

- The Monge formulation wishes to find a mapping  $T : \Omega_s \rightarrow \Omega_t$  that minimises

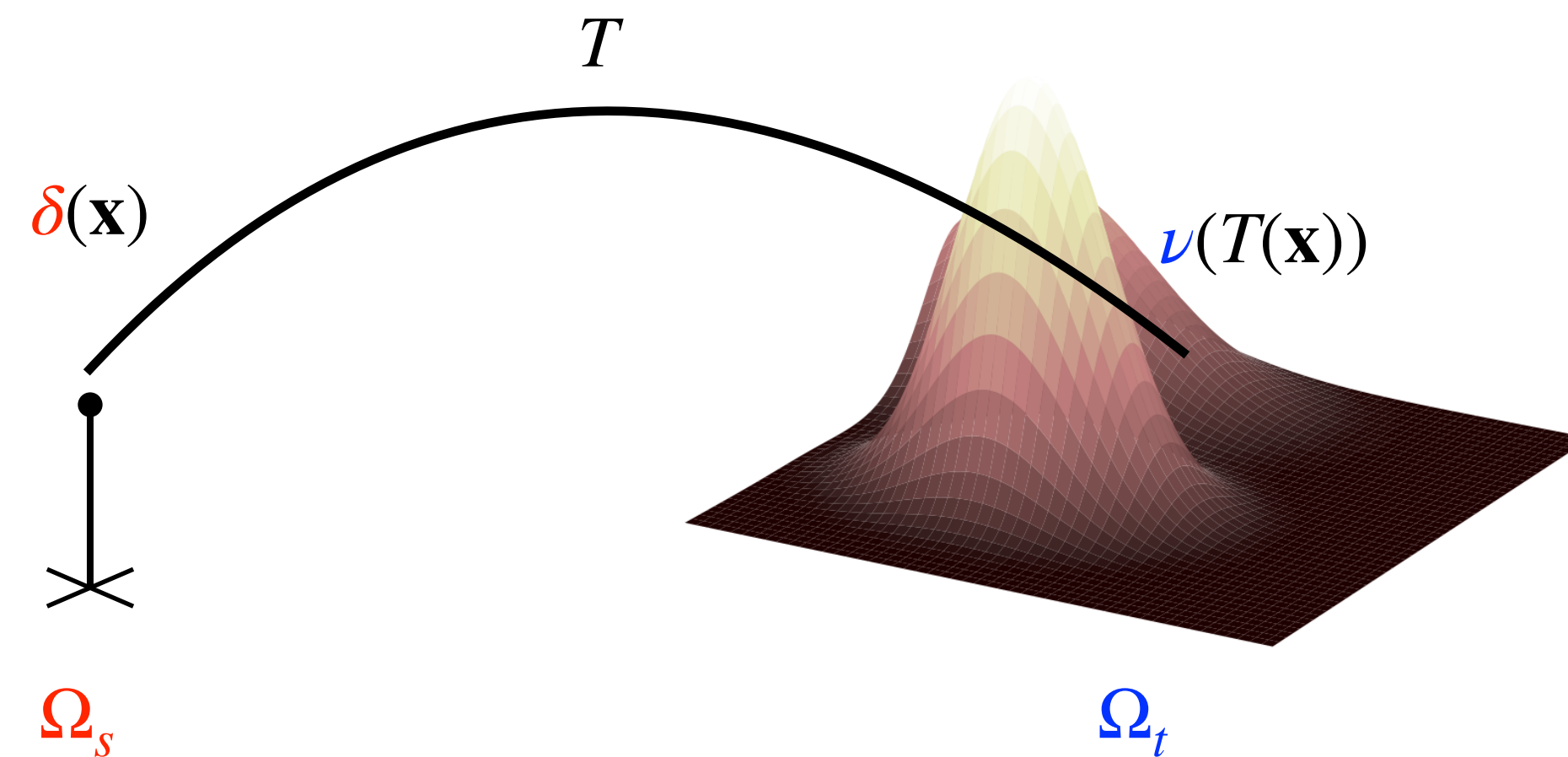
$$\inf_{T\#\mu=\nu} \int_{\Omega_s} c(\mathbf{x}, T(\mathbf{x})) \mu(\mathbf{x}) d\mathbf{x}$$



# Monge Problem - Issues

$$\inf_{T\#\mu=\nu} \int_{\Omega_s} c(\mathbf{x}, T(\mathbf{x}))\mu(\mathbf{x})d\mathbf{x}$$

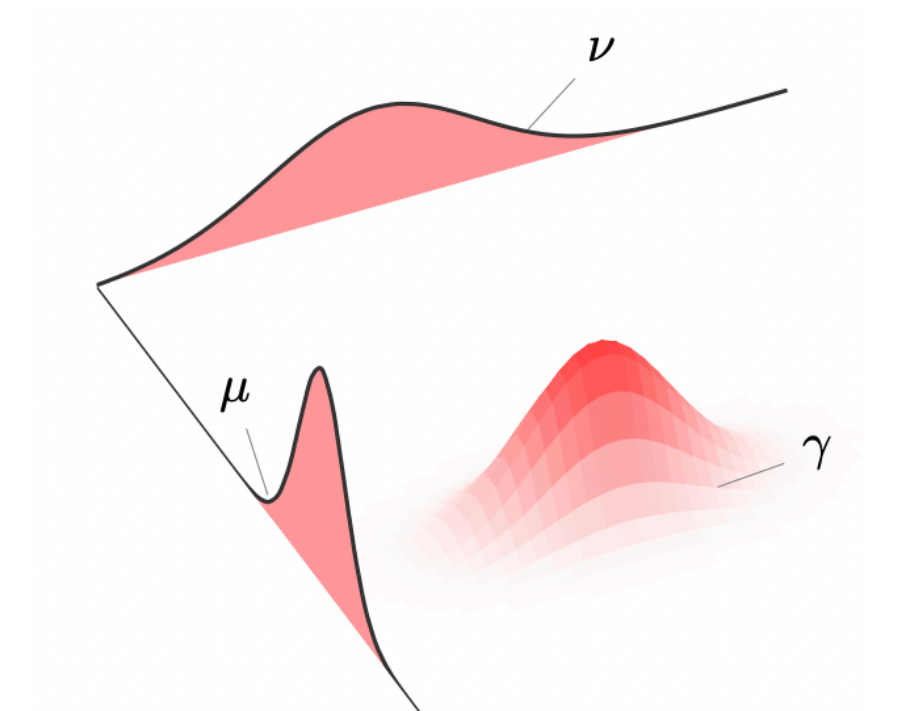
- $T\#\mu = \nu$  is not a convex constraint, *Existence* and *Unicity* of  $T$  is not guaranteed
- Can't split mass (one-to-one, but not one-to-many)
- Ex: Can't map Dirac measures  $\delta_x$  to continuous measures



# Kantorovich Relaxation

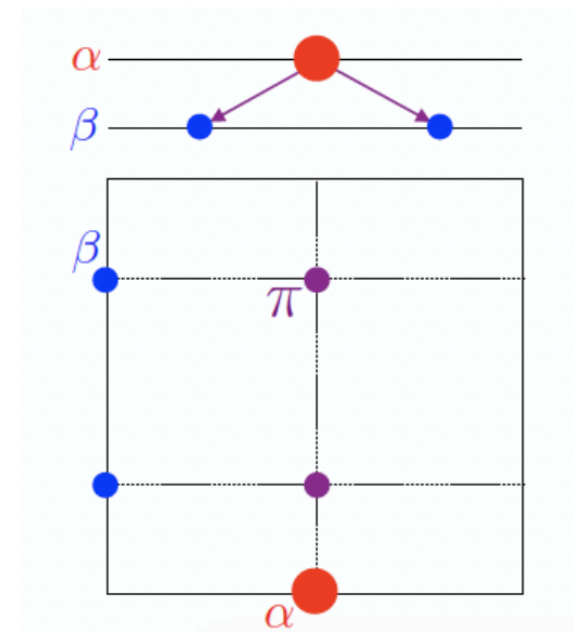
- [Kantorovich, 1942] Relax the requirement of maps  $T$  to *probabilistic couplings*  $\gamma \in \mathcal{P}(\Omega_s \times \Omega_t)$

$$\gamma \in \mathcal{P} = \left\{ \gamma \geq \mathbf{0}, \int_{\Omega_t} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y} = \mu, \int_{\Omega_s} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} = \nu \right\}$$



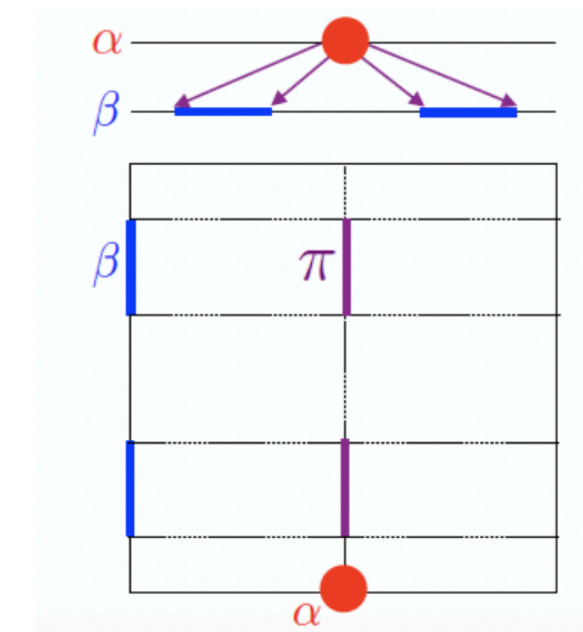
Product Coupling  $\gamma = \mu \otimes \nu$

Image credit: Lenaic Chizat



Coupling for Dirac  $\rightarrow$  Dirac

Image credit: Remi Flamary



Coupling for Dirac  $\rightarrow$  Continuous

Image credit: Remi Flamary

- Given  $\mu \in P(\Omega_s)$ ,  $\nu \in P(\Omega_t)$ , on metric spaces, a cost function  $c : \Omega_s \times \Omega_t \rightarrow \mathbb{R}^+$ , find couplings  $\gamma$  that minimise

$$\operatorname{argmin} \int_{\Omega_s \times \Omega_t} c(\mathbf{x}, \mathbf{y}) \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y} \quad \text{s.t.}$$

$$\gamma \in \mathcal{P} = \left\{ \gamma \geq \mathbf{0}, \int_{\Omega_t} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y} = \mu, \int_{\Omega_s} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} = \nu \right\}$$

# Kantorovich Dual Formulation

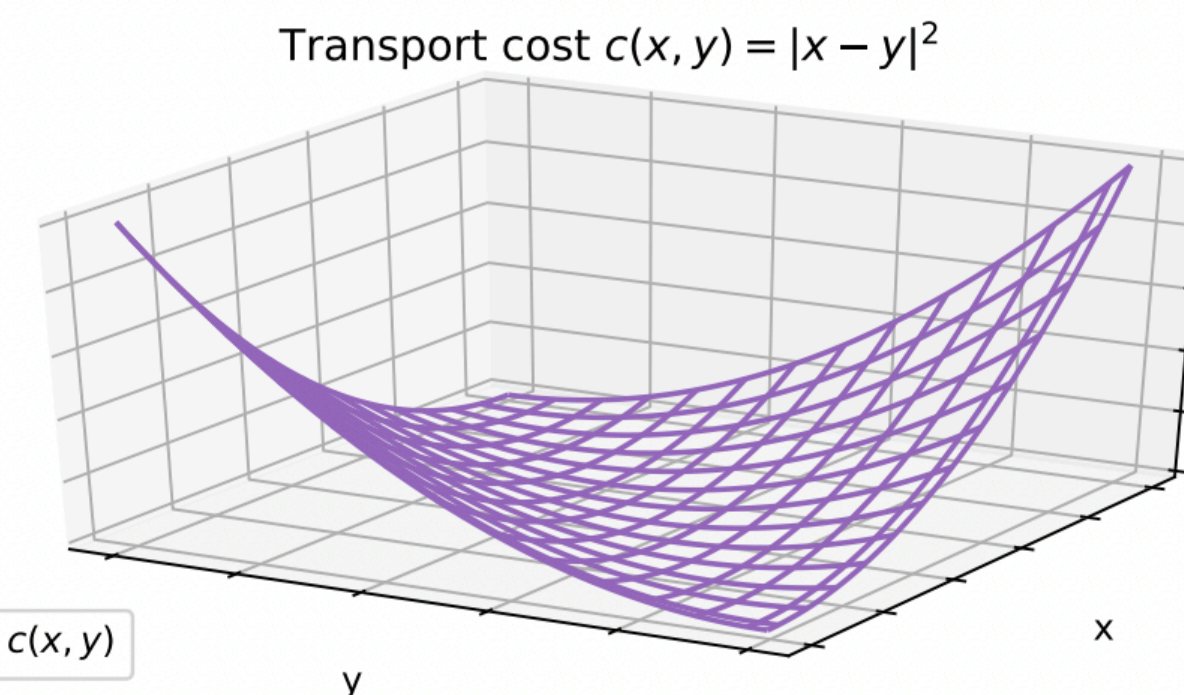
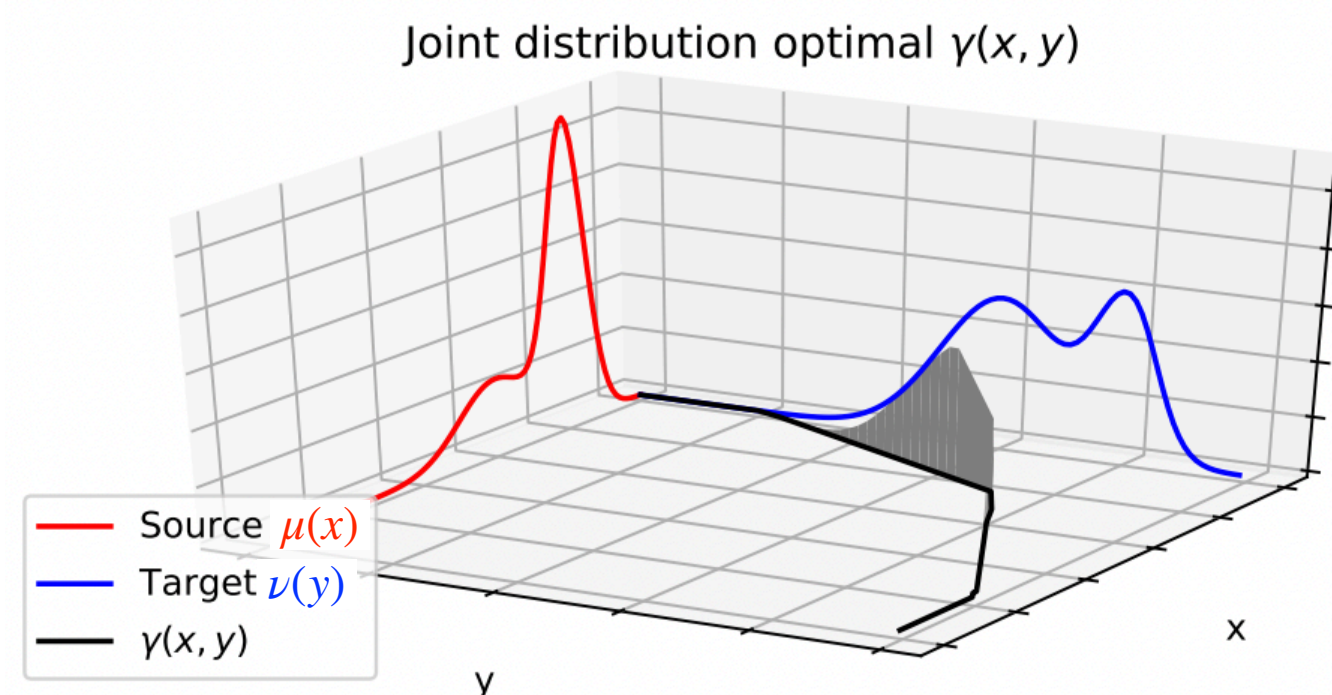
- Instead of optimising over all couplings  $\gamma$  that satisfy the constraints, consider two measurable functions  $\phi \in L_1(\mu)$ ,  $\psi \in L_1(\nu)$

- Reminder: A fn  $f : \mathcal{X} \rightarrow \mathcal{Y}$  is Lipschitz continuous if there exists a real constant  $K \geq 0$  s.t

$$d_{\mathcal{Y}}(f(x_1), f(x_2)) \leq K d_{\mathcal{X}}(x_1, x_2)$$

$$\text{Solve } \max_{\phi, \psi} \left\{ \int \phi d\mu + \int \psi d\nu \quad \text{s.t.} \quad \phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) \right\}$$

- The primal and dual formulations solve exactly the same problem at the equality
- support of  $\gamma(\mathbf{x}, \mathbf{y})$  is where  $\phi(\mathbf{x}) + \psi(\mathbf{y}) = c(\mathbf{x}, \mathbf{y})$





# Semi-dual formulation: c-Conjugates

- Instead of optimising over all possible  $\phi, \psi$  given constraints, can we find the best  $\psi$  given a  $\phi$ ?
- Given a  $\phi$ , we need that  $\psi$  satisfies for all  $\mathbf{x}, \mathbf{y}$

$$\phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y})$$

$$\psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

$$\psi(\mathbf{y}) \leq \inf_{\mathbf{x}} c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

$$\text{define } \phi^c(\mathbf{y}) = \inf_{\mathbf{x}} c(\mathbf{x}, \mathbf{y}) - \phi(\mathbf{x})$$

- Can simplify to a semi-dual formulation that depends on only one function  $\phi$  through the c-conjugate

$$\max_{\phi, \psi} \left\{ \int \phi d\mu + \int \psi d\nu \quad \text{s.t.} \quad \phi(\mathbf{x}) + \psi(\mathbf{y}) \leq c(\mathbf{x}, \mathbf{y}) \right\} \quad \Longrightarrow \quad \max_{\phi} \left\{ \int \phi d\mu + \int \phi^c d\nu \right\}$$

# Wasserstein Distances

- If  $c(x, y) = D^p(x, y)$ , a distance-metric, then for measures  $\mu, \nu \in P(\Omega)$ , the p-Wasserstein Distance is

- $$W_p^p(\mu, \nu) = \left( \inf_{\gamma \in \mathcal{P}} \iint D(x, y)^p \gamma(dx, dy) \right) = \mathbb{E}_{(x, y) \sim \gamma} [D(x, y)^p]$$

- In dual formulation

- $$W_p^p(\mu, \nu) = \sup_{\phi \in L_1(\mu), \psi \in L_1(\nu)} \int \phi d\mu + \int \psi d\nu, \text{ where } \phi(x) + \psi(y) \leq D^p(x, y)$$

- Special Case of semi-dual formulation -  $W_1$  **Distance**

- Proposition: if  $c = |x - y|$ , then  $\phi^c = -\phi$  for all  $\phi$  that are 1-Lipschitz.

- $$W_1(\mu, \nu) = \sup_{\phi \text{ is 1-Lipschitz}} \int \phi(d\mu - d\nu)$$

# Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
- Euclidean distance -> interpolation, barycenters, etc

Wasserstein:  $W_2^2(\alpha, \beta) \stackrel{\text{def.}}{=} \sup_{f,g} \{ \int f d\alpha + \int g d\beta ; f(x) + g(y) \leq \|x - y\|^2 \}$

Hellinger:  $H^2(\alpha, \beta) \stackrel{\text{def.}}{=} \int (\sqrt{\frac{d\alpha}{dx}} - \sqrt{\frac{d\beta}{dx}})^2 dx$

Kullback-Leibler:  $KL(\alpha|\beta) \stackrel{\text{def.}}{=} \int \log(\frac{d\alpha}{d\beta}) d\beta$

Burg:  $B(\alpha|\beta) \stackrel{\text{def.}}{=} KL(\beta|\alpha)$

Gaussian:  $\alpha_m^\sigma \stackrel{\text{def.}}{=} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-m)^2}{2\sigma^2}} dx$

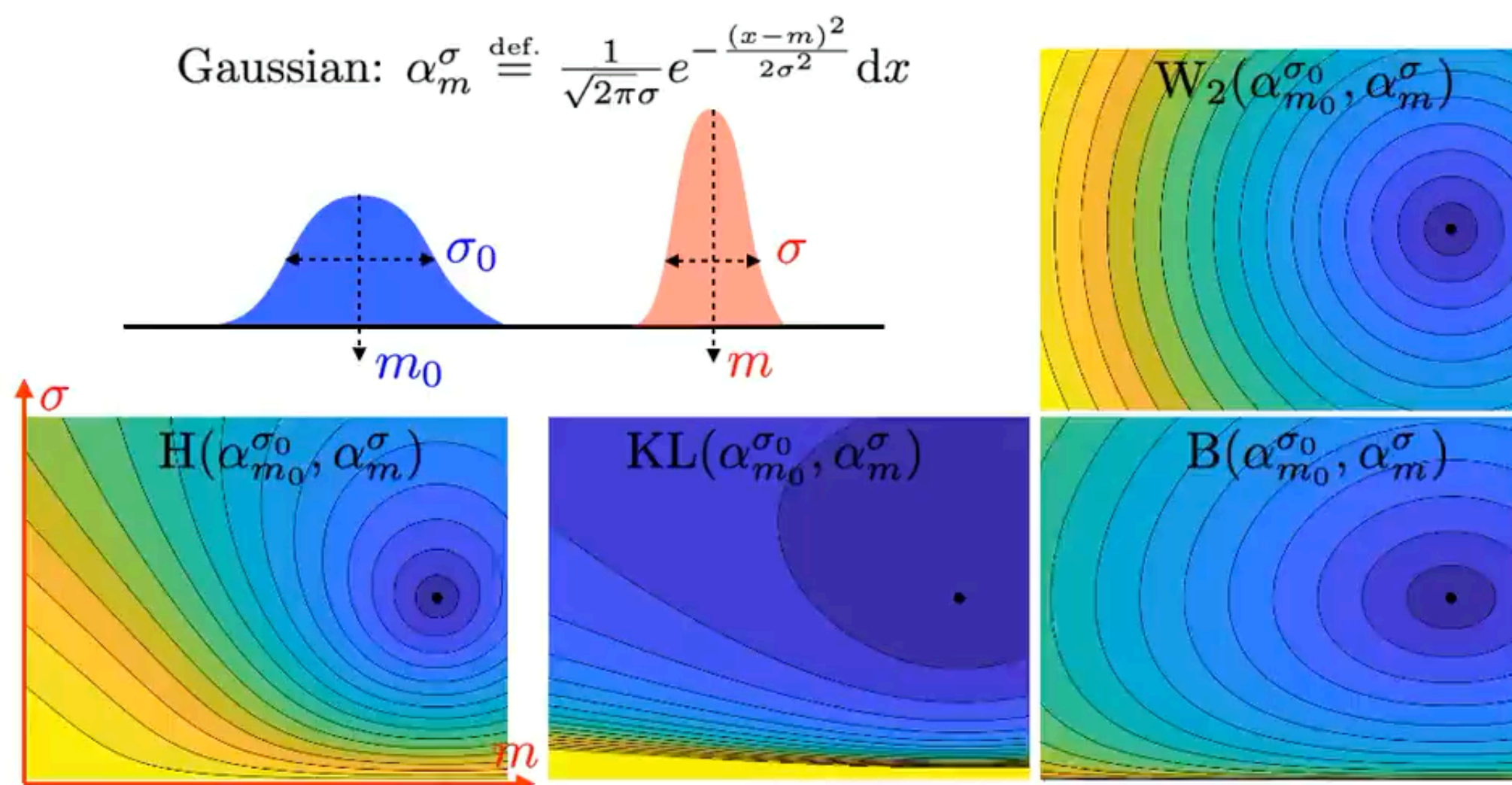


Image credit: Gabriel Peyre

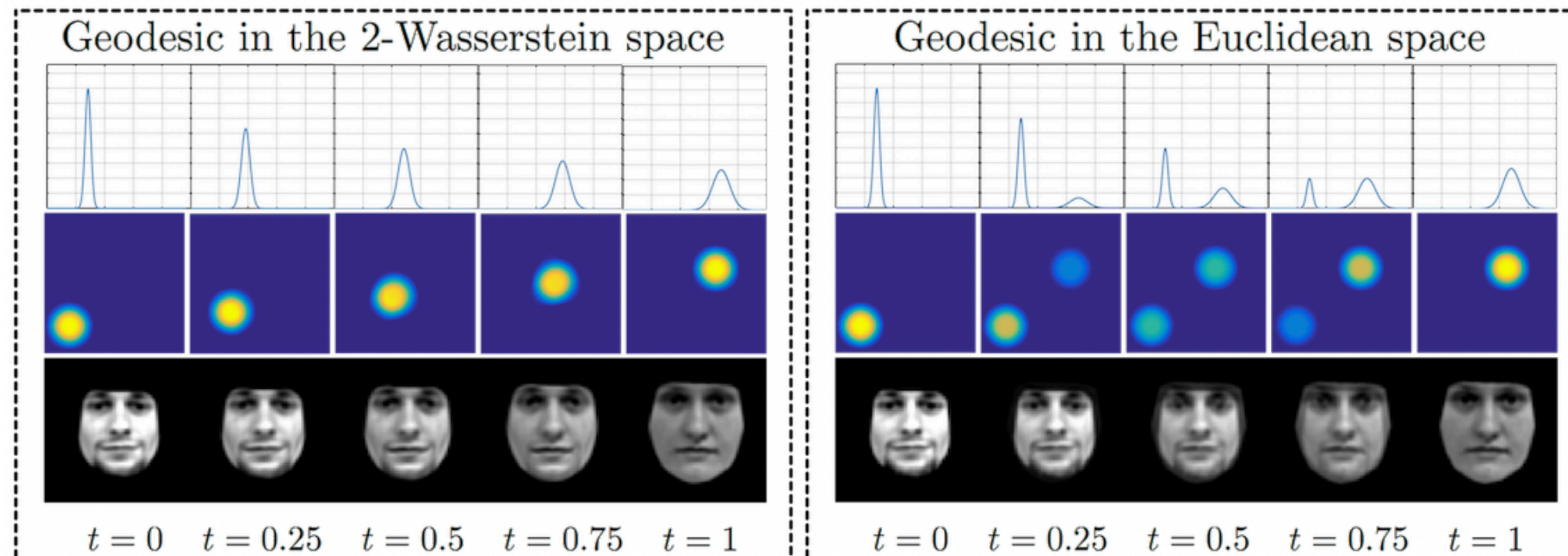


Image credit: [Kolouri et al. 2017]

# Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
  - Euclidean distance  $\rightarrow$  interpolation, barycenters, convexity

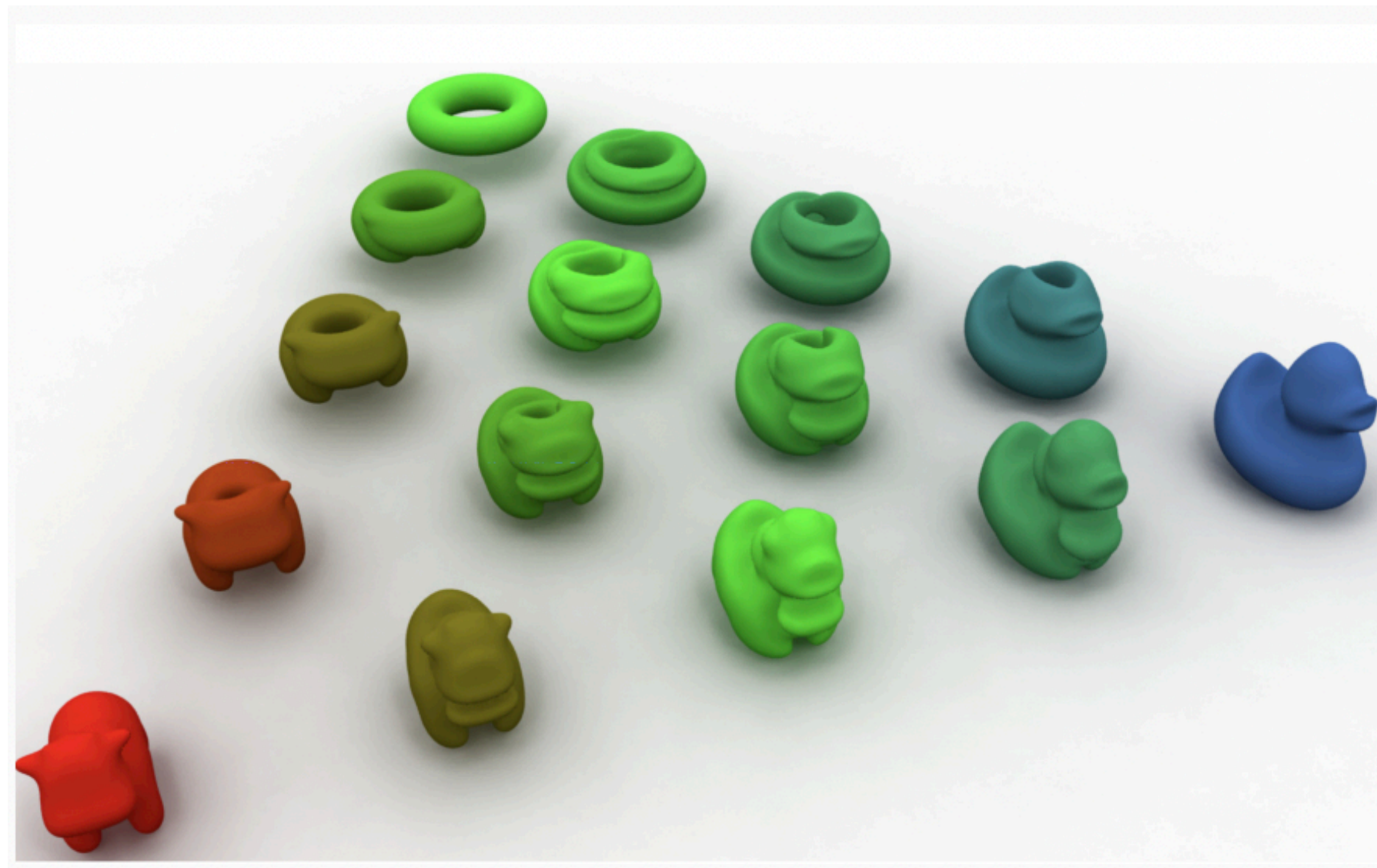
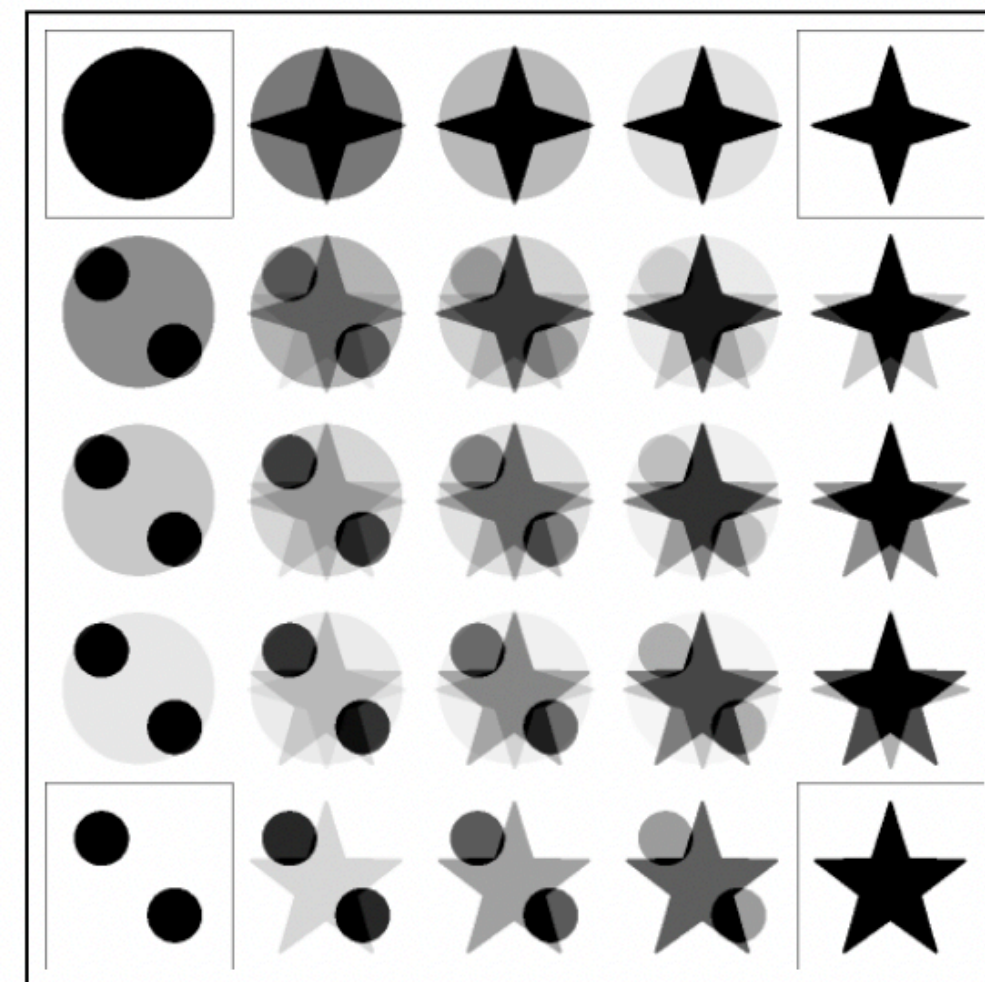
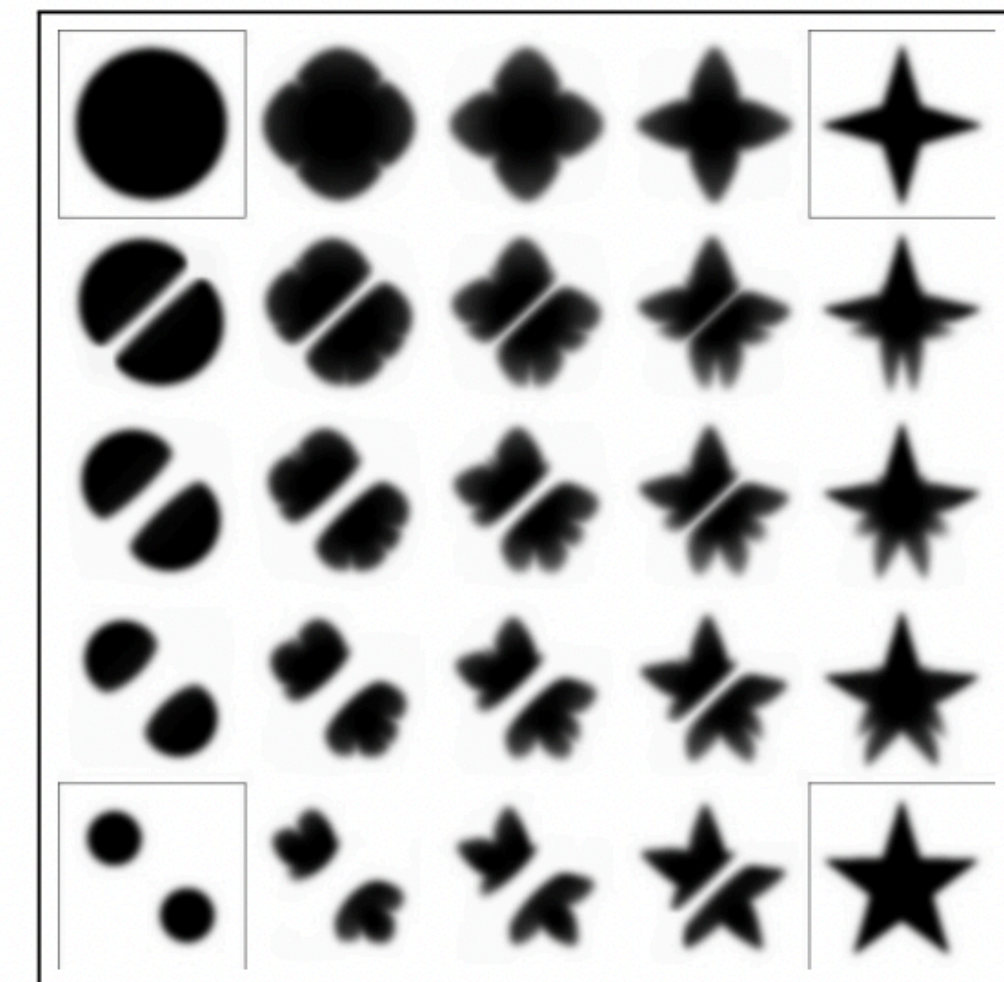


Image credit: [Solomon et al. 2015]



Euclidean barycenter



Wasserstein barycenter

Image credit: [Solomon et al. 2015]

# Wasserstein Distances are natural metrics

- W-distances encode very different geometries from standard information divergences (KL, Euclidean)
- W-distances borrow key properties from the underlying distance metric and port them into the space of probability distributions
  - Euclidean distance  $\rightarrow$  interpolation, barycenters, convexity
- What's the catch?
  - Quite **expensive** to calculate in practice
  - **Not differentiable** generally
  - Statistical properties **don't scale to high-D distributions**

# Example - OT for Discrete Distributions

- Consider discrete measures  $\mu = \sum_i^n a_i \delta_{\mathbf{x}_i}$ ,  $\nu = \sum_i^m b_j \delta_{\mathbf{y}_j}$ , where  $\mathbf{x}_i, \mathbf{y}_j \in \Omega$ , and  $\sum_i^n a_i = 1$ ,  $\sum_j^m b_j = 1$
- Langrangian point clouds ( $a_i = \frac{1}{n}$ ,  $b_j = \frac{1}{m}$ ), Eulerian Histograms ( $\mathbf{x}_i, \mathbf{y}_j$  are points on a grid)

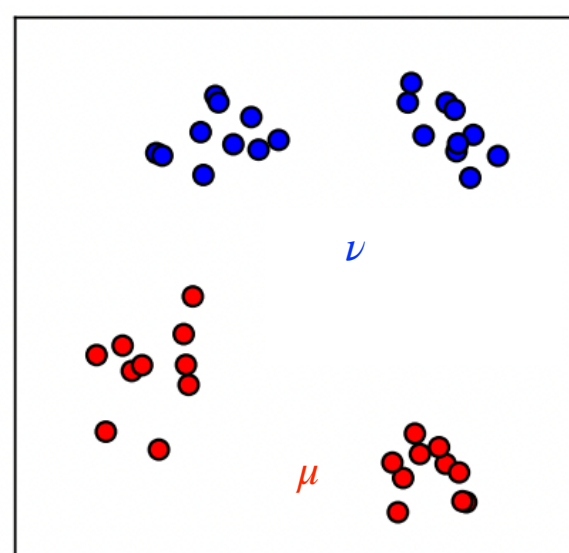


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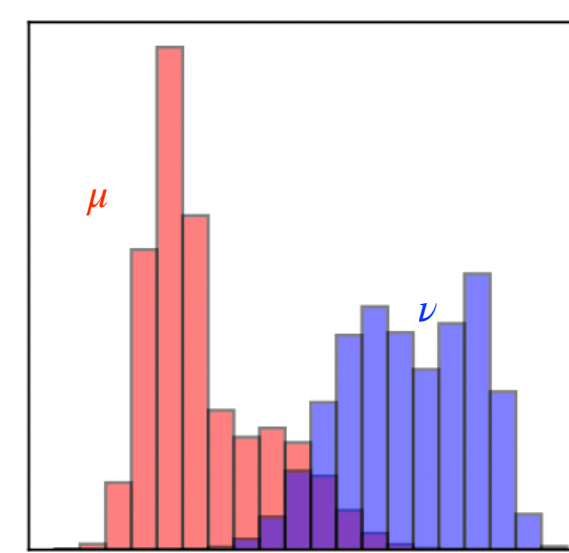


Image credit: Remi Flamary

- Given a cost matrix  $\mathbf{C} = c(\mathbf{x}_i, \mathbf{y}_j)$ , the optimal coupling between measures is a linear program given by

$$\gamma_0 = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \mathbf{C}, \gamma \rangle_F = \sum_{i,j} \gamma_{i,j} c_{i,j} \text{ where } \mathcal{P} = \left\{ \gamma \in (\mathbb{R}^+)^{n \times m} \mid \gamma \mathbf{1}_n = \mathbf{a}, \gamma \mathbf{1}_m = \mathbf{b} \right\}$$

- Alternative dual formulation is given by  $n + m$  variables and  $nm$  constraints

$$\max_{\alpha \in \mathbb{R}^n, \beta \in \mathbb{R}^m} \alpha^T \mathbf{a} + \beta^T \mathbf{b} \quad \text{s.t. } \alpha_i + \beta_j \leq c_{i,j} \quad \forall i, j$$

# OT for Discrete Distributions - Issues

- Linear Program - no unique solution sometimes, numerical instabilities
  - $W_p^p(\mu, \nu)$  is not differentiable
  - Not parallelisable on GPU hardware
  - Solving a linear problem is  $\mathcal{O}((n+m)nm \log(n+m))$
- Assuming we have samples  $x_1, \dots, x_n \sim \mu, y_1, \dots, y_m \sim \nu$ , what are the considerations involved when computing  $W_p^p(\hat{\mu}_n, \hat{\nu}_m)$ , where  $\hat{\mu}_n = \frac{1}{n} \sum_i \delta_{x_i}, \hat{\nu}_m = \frac{1}{m} \sum_j \delta_{y_j}$ ?
- Can we bound  $\mathbb{E} \left[ \left| W_p(\mu, \nu) - W_p(\hat{\mu}_n, \hat{\nu}_m) \right| \right]$ ?
- [Peyre et al., 15] If  $\Omega = \mathbb{R}^d, d > 3$  then  $\mathbb{E} \left[ \left| W_p(\mu, \nu) - W_p(\hat{\mu}_n, \hat{\nu}_m) \right| \right] = \mathcal{O}(n^{-1/d})$
- What machine learning applications would ideally like
  - Faster, scalable, more stable, differentiable (ideally using autodiff), better statistical convergence

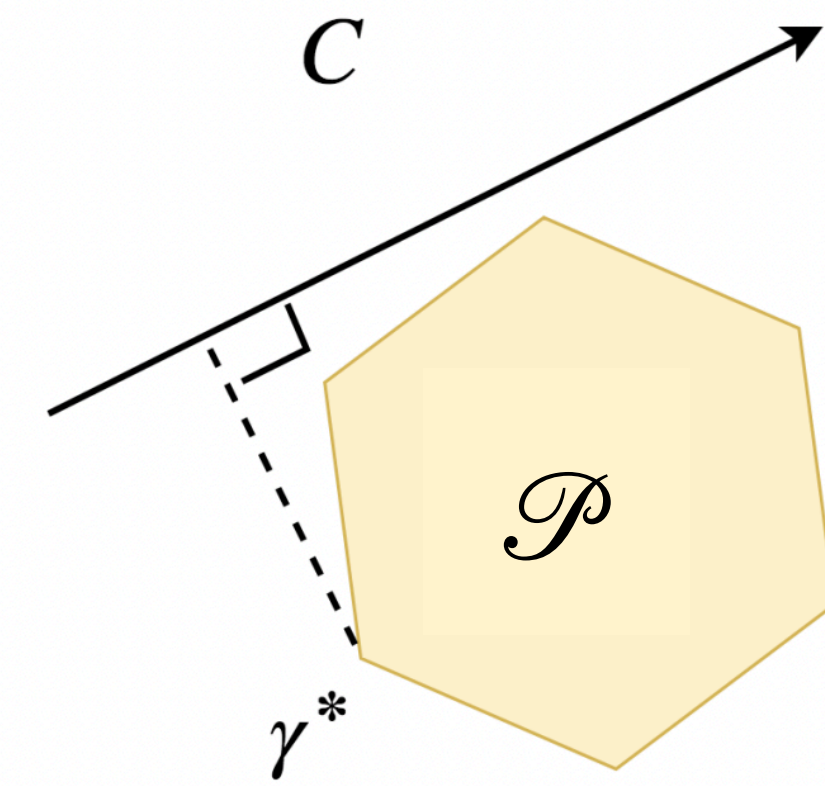


Image credit: Remi Flamary

# Approximate/Regularised OT



# Sliced Wasserstein Distances

- For 1-D distributions  $\Omega \in \mathbb{R}$ , the  $W_p$  Distance is a function of the quantile functions  $F_{\mu}^{-1}(x)$ ,  $F_{\nu}^{-1}(x)$

$$W_p(\mu, \nu) = \int_0^1 c \left( \left| F_{\mu}^{-1}(x) - F_{\nu}^{-1}(x) \right|^p \right) dx$$

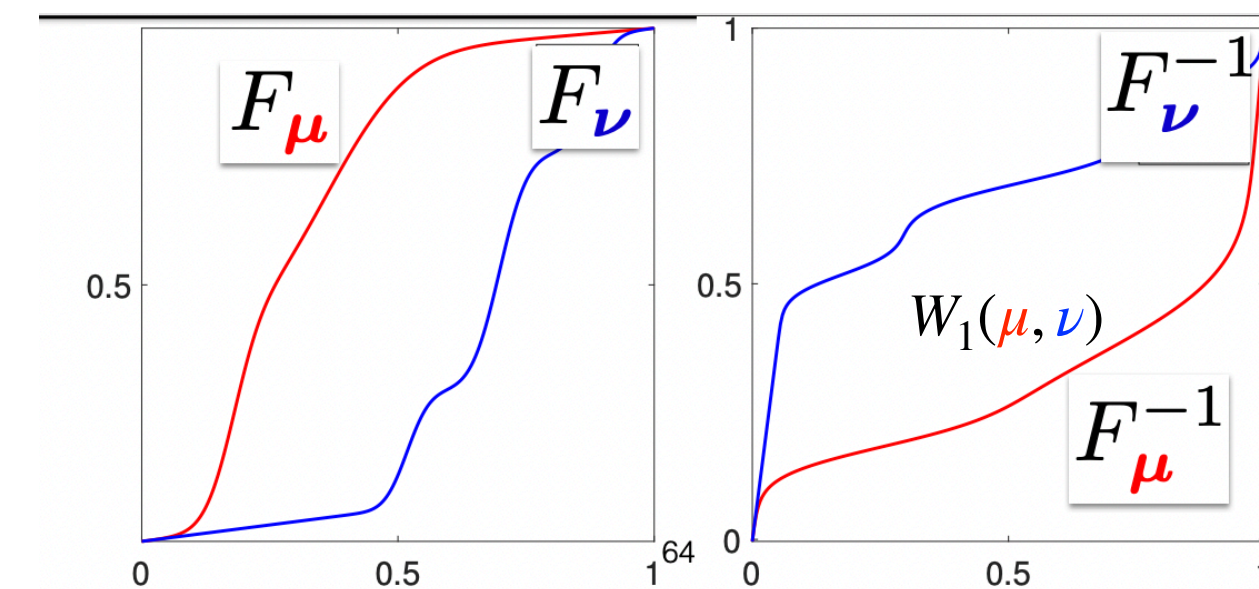


Image credit: Marco Cuturi

- For discrete distributions, very fast  $\mathcal{O}(n \log n)$  algorithms exist
- Idea - Project the high-dimensional distributions into 1 dimension, and calculate 1-D  $W_p$  distances**
- [Bonneel et al. 2015, Kolouri et al. 2017] accomplish this using the Radon Transform

$$\mathcal{R}(\mu, \theta) = \int_{\mathbb{S}^{d-1}} \delta(t - x^T \theta) \mu(x) dx, \quad t \in \mathbb{R}, \quad \theta \in \mathbb{S}^{d-1}$$

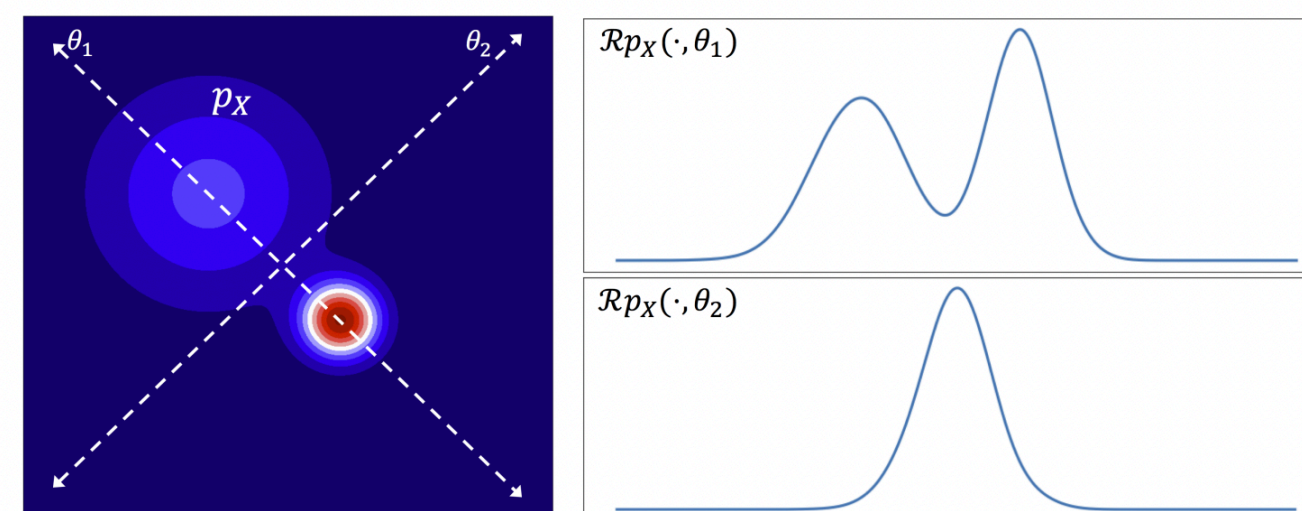


Image credit: [Kolouri et al 2017]

# Sliced Wasserstein Distances

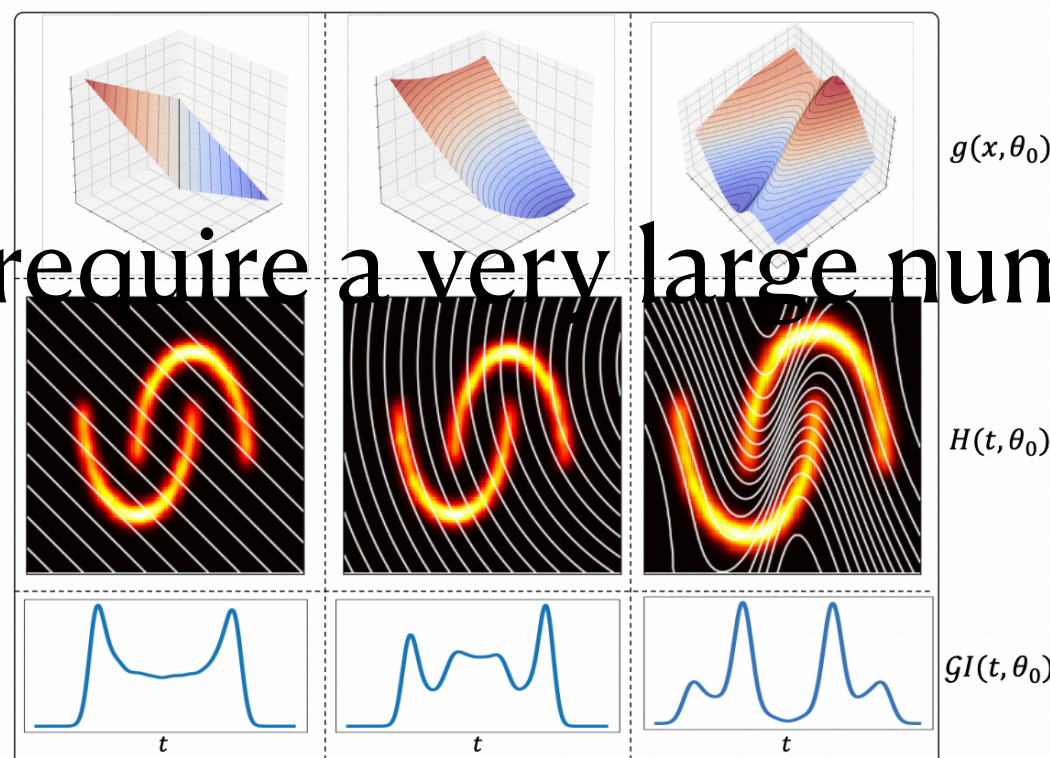
- [Bonneel et al. 2015] p-sliced Wasserstein distance

$$pSW_p^p(\mu, \nu) = \int_{\mathbb{S}^{d-1}} W_p^p(\mathcal{R}(\mu, \theta), \mathcal{R}(\nu, \theta)) d\theta$$

$$pSW_{p,K}^p(\mu, \nu) = \sum_l \frac{1}{K} W_p^p(\mathcal{R}(\mu, \theta_l), \mathcal{R}(\nu, \theta_l)), \quad \mathcal{O}(Kn \log n)$$

- [Nadjahi et al, 2020] sliced W-distances are true metrics, topologically equivalent and weaker to  $W_p$ 
  - Statistical convergence  $\sim \mathcal{O}(K^{-1/2}n^{-1/2})$
  - [Kolouri et al, 2020] generalise this distance by formulating generalised Radon transforms onto general hyper-surfaces

- Still not differentiable, in practise can require a very large number of MC estimates if d is large



# Regularised Optimal Transport

- **Idea - OT with Regularisation**

- Option 1: Add priors to the family of couplings to consider

- Add a regularisation term to the OT formulation,  $\gamma_0^\lambda = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F + \lambda R(\gamma)$

- [Cuturi, 2013] Entropic Regularisation,  $R(\gamma) = \sum_{i,j} \gamma_{i,j} (\log \gamma_{i,j} - 1)$

- [Courty et al., 2016] Group Lasso,  $R(\gamma) = \sum_g \sqrt{\sum_{i,j \in \mathcal{G}_g} \gamma_{i,j}^2}$

- Option 2: Relax the requirement for  $W_1(\mu, \nu) = \sup_{\phi \text{ is 1-Lipschitz}} \int \phi(d\mu - d\nu)$

- [Makkouva et al., 17] Use RELU Networks with bounded weights

- [Shirdhonkar'08] - Use low-dimensional wavelet decompositions

- Option 3: Change the cost function in  $\operatorname{argmin}_{\gamma \in \mathcal{P}} \int_{\Omega_s \times \Omega_t} c(\mathbf{x}, \mathbf{y}) \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x} d\mathbf{y}$

- [Solomon+, '17] Geodesic Distances on graphs simplify the Linear Program

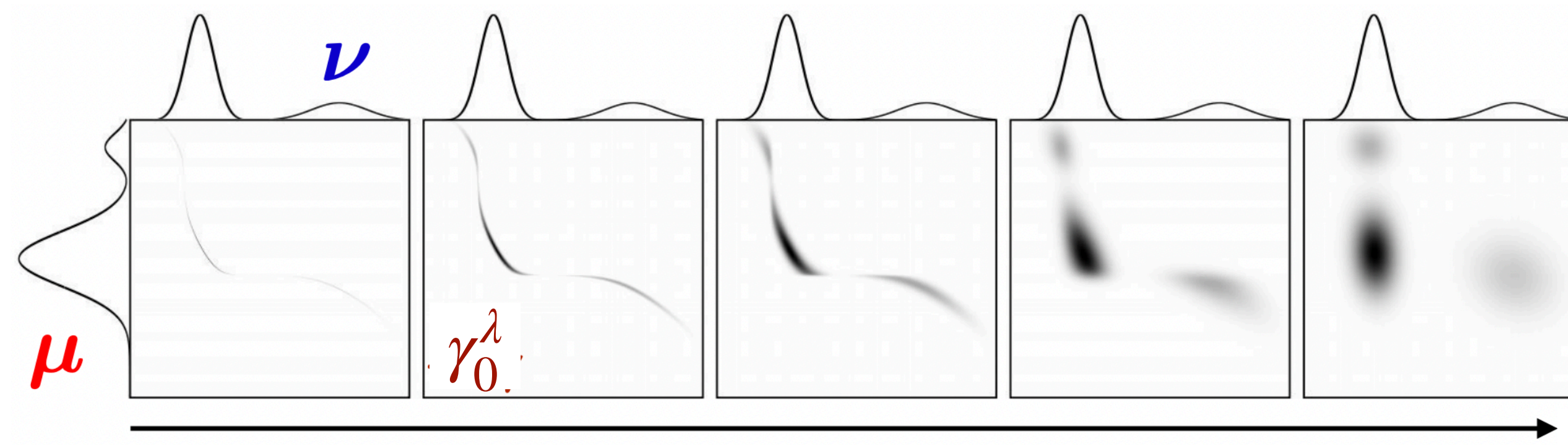
# Entropic Regularised OT

- We have  $\gamma_0^\lambda = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F + \lambda \sum_{i,j} \gamma_{i,j} (\log \gamma_{i,j} - 1) = \operatorname{argmin}_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$

- [Wilson, '69] Define a regularised Wasserstein distance, for  $\lambda \geq 0$

$$W_\lambda(\mu, \nu) = \min_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$$

- If  $\lambda \geq 0$ , then the linear program becomes a  $\lambda$ -strongly convex optimisation problem
- Fast and scalable, differentiable - **Sinkhorn's Algorithm**
  - $\mathcal{O}(nm)$  complexity in general,  $\simeq \mathcal{O}(n \log n)$  on gridded spaces with convolutions [Solomon et al., '15]
- Better statistical convergence properties - **Sinkhorn Divergences**



# Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Proposition: If  $\gamma_0^\lambda = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$ , then there exists  $\mathbf{u} \in \mathbb{R}_+^n, \mathbf{v} \in \mathbb{R}_+^m$  such that

$$\gamma_0^\lambda = \operatorname{diag}(\mathbf{u}) \mathbf{K} \operatorname{diag}(\mathbf{v}), \text{ where } \mathbf{K} = e^{-\mathbf{C}/\lambda}$$

- Write down the Lagrangian to solve the convex optimisation problem

$$L(\gamma, \alpha, \beta) = \sum_{ij} \gamma_{i,j} \mathbf{C}_{i,j} + \lambda \gamma_{i,j} (\log \gamma_{i,j} - 1) + \alpha^T (\gamma \mathbf{1} - \mathbf{a}) + \beta^T (\gamma^T \mathbf{1} - \mathbf{b})$$

$$\partial L / \partial \gamma_{i,j} = \mathbf{C}_{i,j} + \lambda \log \gamma_{i,j} + \alpha_i + \beta_j \Rightarrow 0$$

$$\gamma_{i,j} = e^{\frac{\alpha_i}{\lambda}} e^{-\frac{\mathbf{C}_{i,j}}{\lambda}} e^{\frac{\beta_j}{\lambda}} = u_i K_{ij} v_j$$

# Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Proposition: If  $\gamma_0^\lambda = \underset{\gamma \in \mathcal{P}}{\operatorname{argmin}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$ , then there exists  $\mathbf{u} \in \mathbb{R}_+^n, \mathbf{v} \in \mathbb{R}_+^m$  such that

$$\gamma_0^\lambda = \operatorname{diag}(\mathbf{u}) \mathbf{K} \operatorname{diag}(\mathbf{v}), \text{ where } \mathbf{K} = e^{-\mathbf{C}/\lambda}$$

- To solve, first use the marginalisation constraints

$$\begin{cases} \operatorname{diag}(\mathbf{u}) \mathbf{K} \operatorname{diag}(\mathbf{v}) \mathbf{1}_m = \mathbf{a} \\ \operatorname{diag}(\mathbf{v}) \mathbf{K}^T \operatorname{diag}(\mathbf{u}) \mathbf{1}_n = \mathbf{b} \\ \mathbf{u} \odot \mathbf{K} \mathbf{v} = \mathbf{a} \\ \mathbf{v} \odot \mathbf{K}^T \mathbf{u} = \mathbf{b} \end{cases}$$

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]

$$\mathbf{u} \leftarrow \mathbf{a} / \mathbf{K} \mathbf{v} \quad \text{followed by} \quad \mathbf{v} \leftarrow \mathbf{b} / \mathbf{K}^T \mathbf{u}$$

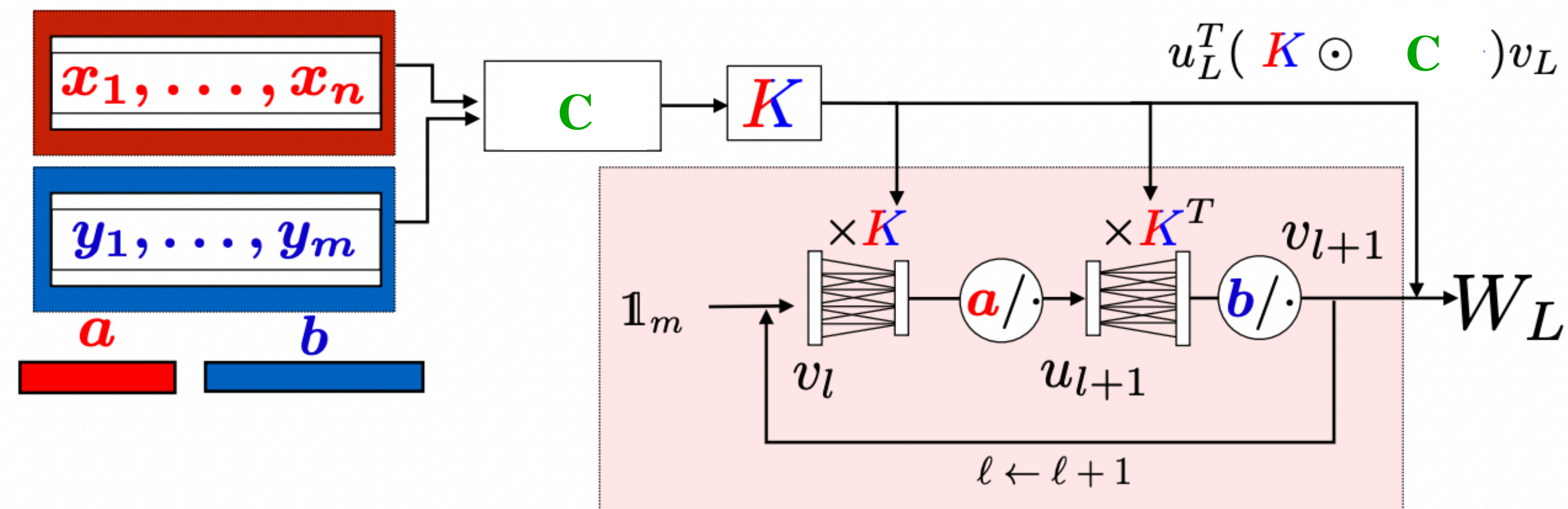
# Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]

$$\mathbf{u} \leftarrow \mathbf{a}/\mathbf{K}\mathbf{v} \quad \text{followed by} \quad \mathbf{v} \leftarrow \mathbf{b}/\mathbf{K}^T\mathbf{u}$$

- Define the iterative Wasserstein Distance

$$W_L(\mu, \nu) = \langle \gamma_L, \mathbf{C} \rangle, \quad \text{where } \gamma_L = \text{diag}(\mathbf{u}_L)\mathbf{K} \text{diag}(\mathbf{v}_L)$$



**Sinkhorn**  $l = 1, \dots, L - 1$

Image credit: Marco Cuturi

- $\frac{\partial W_L}{\partial \mathbf{X}}, \frac{\partial W_L}{\partial \mathbf{a}}, \frac{\partial W_L}{\partial \mathbf{Y}}, \frac{\partial W_L}{\partial \mathbf{b}}$  can be computed recursively (and using autodiff)

# Sinkhorn's Algorithm - A Fast and Scalable OT Solver

- Computational complexity -  $\mathcal{O}((n + m)^2) \times \mathcal{O}(d^2)$
- Linear convergence for  $\mathbf{u}, \mathbf{v} \rightarrow$  Rate bounded by  $\lambda$

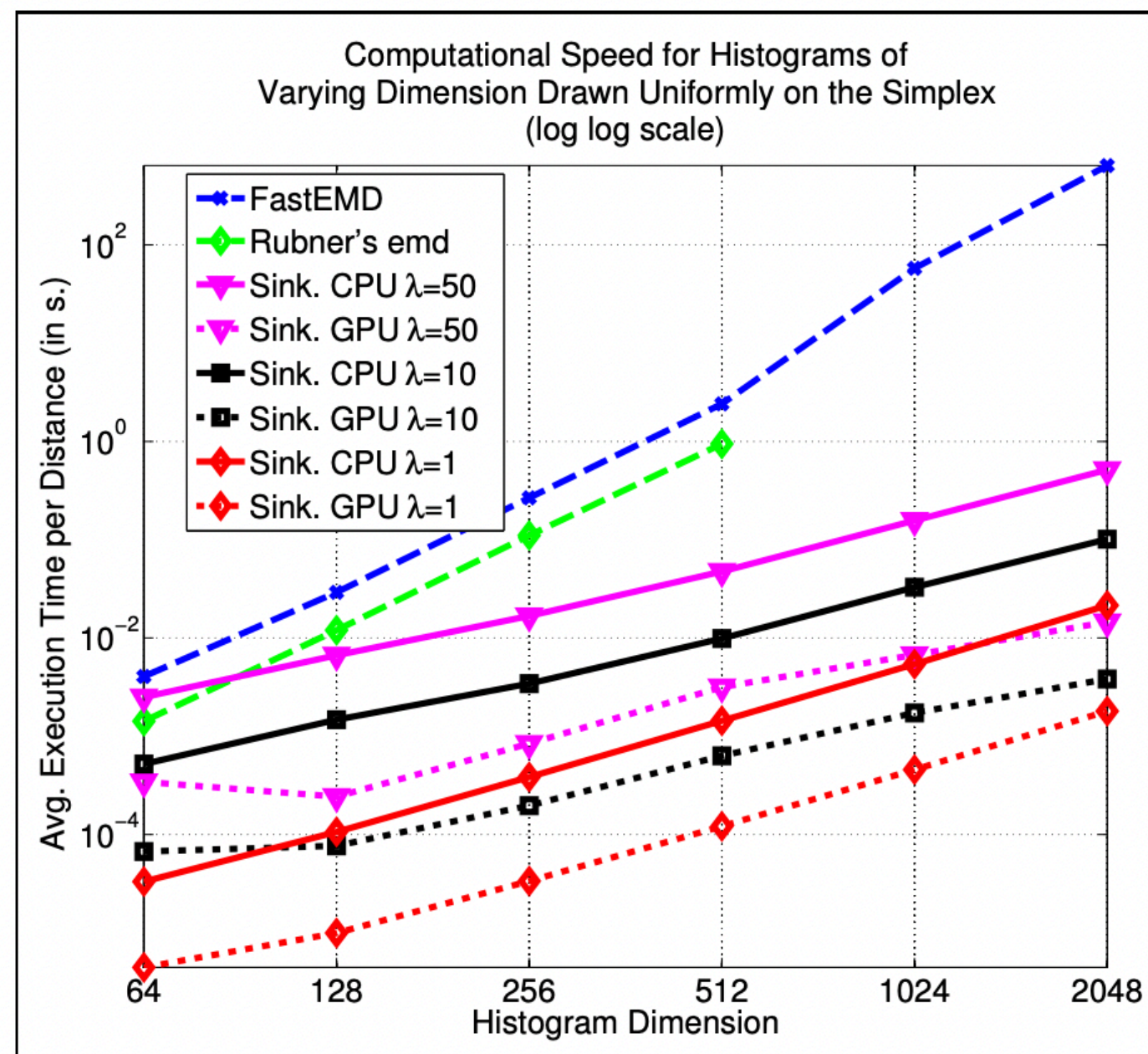


Image credit: [Cuturi et al., 2013]

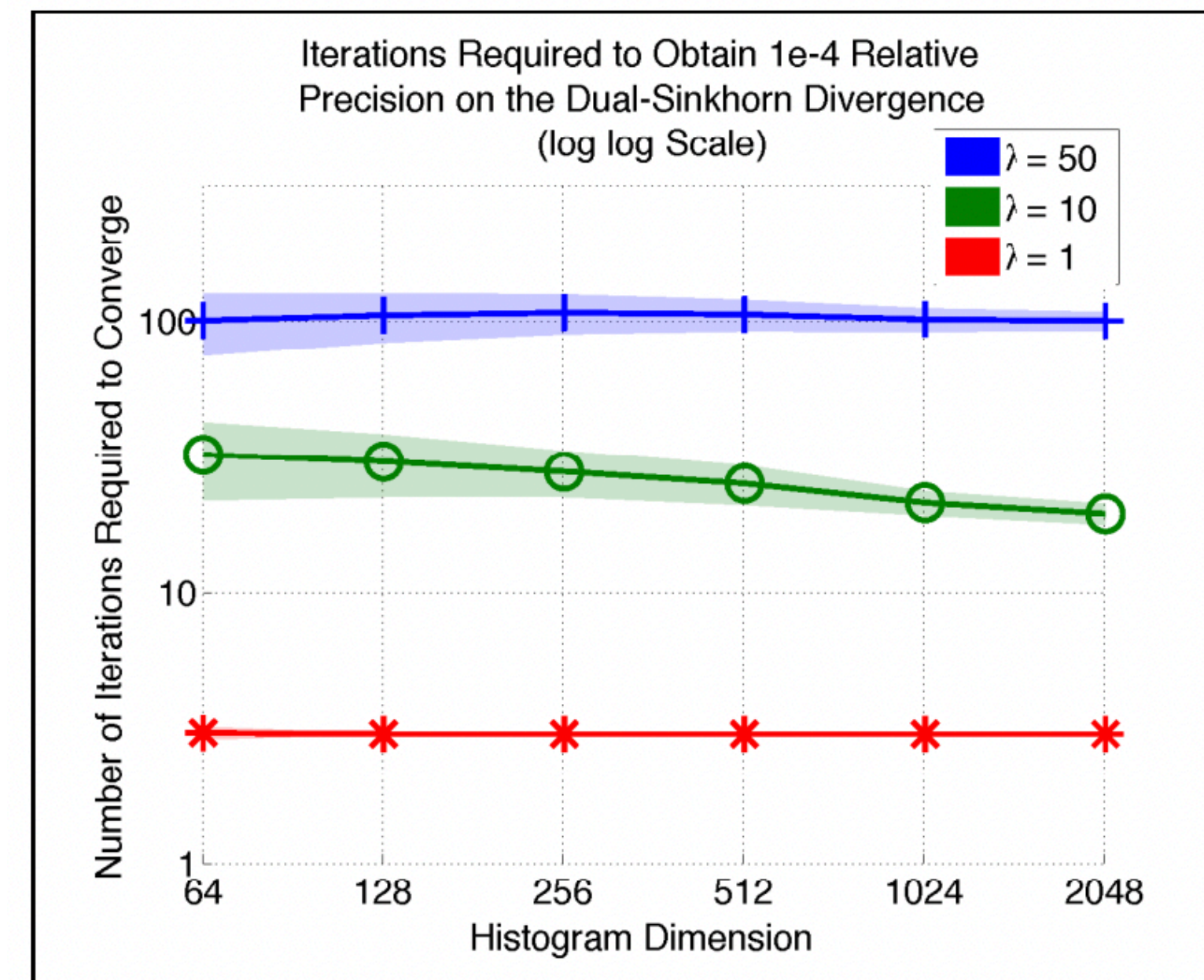


Image credit: [Cuturi et al., 2013]



# Sinkhorn's Algorithm as Bregman Projections

- Fixed-point algorithm, repeat until convergence [Sinkhorn, '67]

$$\mathbf{u} \leftarrow \mathbf{a}/\mathbf{K}\mathbf{v} \quad \text{followed by} \quad \mathbf{v} \leftarrow \mathbf{b}/\mathbf{K}^T\mathbf{u}$$

- [Benamou et al., 2015] show that solving entropic regularised OT is the same as Bregman projections

- Proposition:  $\gamma_0^\lambda$  is the solution of the following Bregman projection

$$\gamma_0^\lambda = \operatorname{argmin}_{\gamma \in \mathcal{P}} \operatorname{KL}(\gamma, \mathbf{K})$$

- Can be generalised to calculate Wasserstein barycenters

$$\min_{\mu} \sum_{i=1}^N \lambda_i W_\lambda(\mu, \nu_i) \quad \rightarrow \quad \gamma = [\gamma_1, \dots, \gamma_N] = \operatorname{argmin}_{\gamma \in \mathcal{P}_i^K} \sum_i \lambda_i \operatorname{KL}(\gamma_i, \mathbf{K})$$

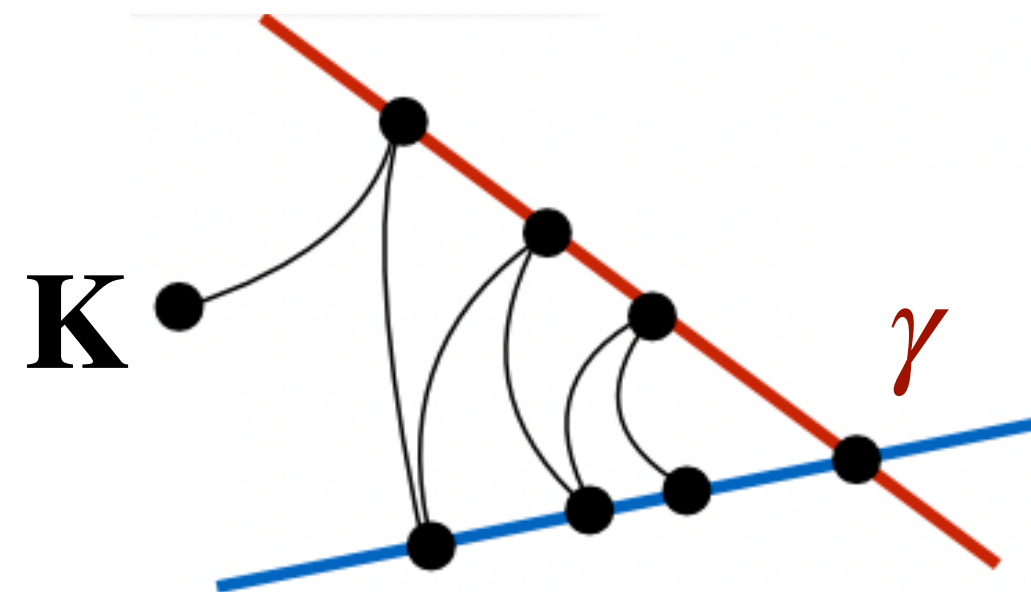


Image credit: Marco

# Sinkhorn Divergences

- Given the regularised Wasserstein Distance  $W_\lambda(\mu, \nu) = \min_{\gamma \in \mathcal{P}} \langle \gamma, \mathbf{C} \rangle_F - \lambda \mathbb{H}(\gamma)$ 
  - Issue:  $W_\lambda(\mu, \mu) \neq 0$
  - Fix [Raudas et al., 2017]:  $\bar{W}_\lambda(\mu, \nu) = W_\lambda(\mu, \nu) - \frac{1}{2}W_\lambda(\mu, \mu) - \frac{1}{2}W_\lambda(\nu, \nu)$ 
    - Sinkhorn Divergences have some nice distance-based and interpolating properties
    - When  $\lambda \rightarrow 0$ , we re-obtain OT
      - $\lim_{\lambda \rightarrow 0} \bar{W}_\lambda(\mu, \nu) = W_p^p(\mu, \nu)$
    - When  $\lambda \rightarrow \infty$ , we obtain kernel-based distances (Maximum Mean Discrepancy, Energy Distance)
      - $\lim_{\lambda \rightarrow \infty} \bar{W}_\lambda(\mu, \nu) = E(\mu, \nu) - \frac{1}{2}E(\mu, \mu) - \frac{1}{2}E(\nu, \nu)$ , where  $E(\mu, \nu) = \langle \mathbf{ab}^T, \mathbf{C} \rangle$

# Sinkhorn Divergences

- Assuming we have samples  $x_1, \dots, x_n \sim \mu, y_1, \dots, y_m \sim \nu$ , what are the considerations involved when computing  $W_p^p(\hat{\mu}_n, \hat{\nu}_m)$ , where  $\hat{\mu}_n = \frac{1}{n} \sum_i \delta_{x_i}, \hat{\nu}_m = \frac{1}{m} \sum_j \delta_{y_j}$ ?

## Computational Costs

## Statistical Convergence

$$(n + m)^2$$

$$MMD(\mu, \nu) = E(\mu, \nu) - \frac{1}{2}E(\mu, \mu) - \frac{1}{2}E(\nu, \nu)$$

$$\mathcal{O}(1/\sqrt{n})$$

$$\uparrow \lambda \rightarrow \infty$$

$$\mathcal{O}((n + m)^2)$$

$$\bar{W}_\lambda(\mu, \nu) = W_\lambda(\mu, \nu) - \frac{1}{2}W_\lambda(\mu, \mu) - \frac{1}{2}W_\lambda(\nu, \nu)$$

$$\mathcal{O}\left(\frac{1}{\lambda^{d/2}\sqrt{n}}\right)$$

$$\downarrow \lambda \rightarrow 0$$

$$\mathcal{O}((n + m)nm \log nm)$$

$$W_p^p(\mu, \nu)$$

$$\mathcal{O}(1/n^{1/d})$$

# **Applications in Machine Learning**

# OT for Supervised Learning - Wasserstein Loss

- [Frogner et al 2015] Multiclass classification - learn optimal maps from  $\mathcal{X} \in \mathbb{R}^d$  to  $\mathcal{Y} = \mathbb{R}_+^K$  through  $\mathcal{H} = h_\theta : \mathcal{X} \rightarrow \mathcal{Y}$ 
  - $h_\theta, y \in \Delta^k$  (the K-d simplex), and  $\mathbf{C} \in \mathbb{R}_+^{K,K}$  where  $\mathbf{C}_{\kappa, \kappa'} = d^p(\kappa, \kappa')$
  - Minimise the entropic regularised Wasserstein Distance  $W_p^\lambda(h(\cdot | x), y(\cdot))$
  - Ground-truth metric can encode semantic similarity
    - Flickr Creative Commons 100M dataset :  $d^p(\kappa, \kappa') = \|\text{word2vec}(\kappa) - \text{word2vec}(\kappa')\|_2^2$
    - Example labels - travel, square, wedding, art, flower, music, nature, ...

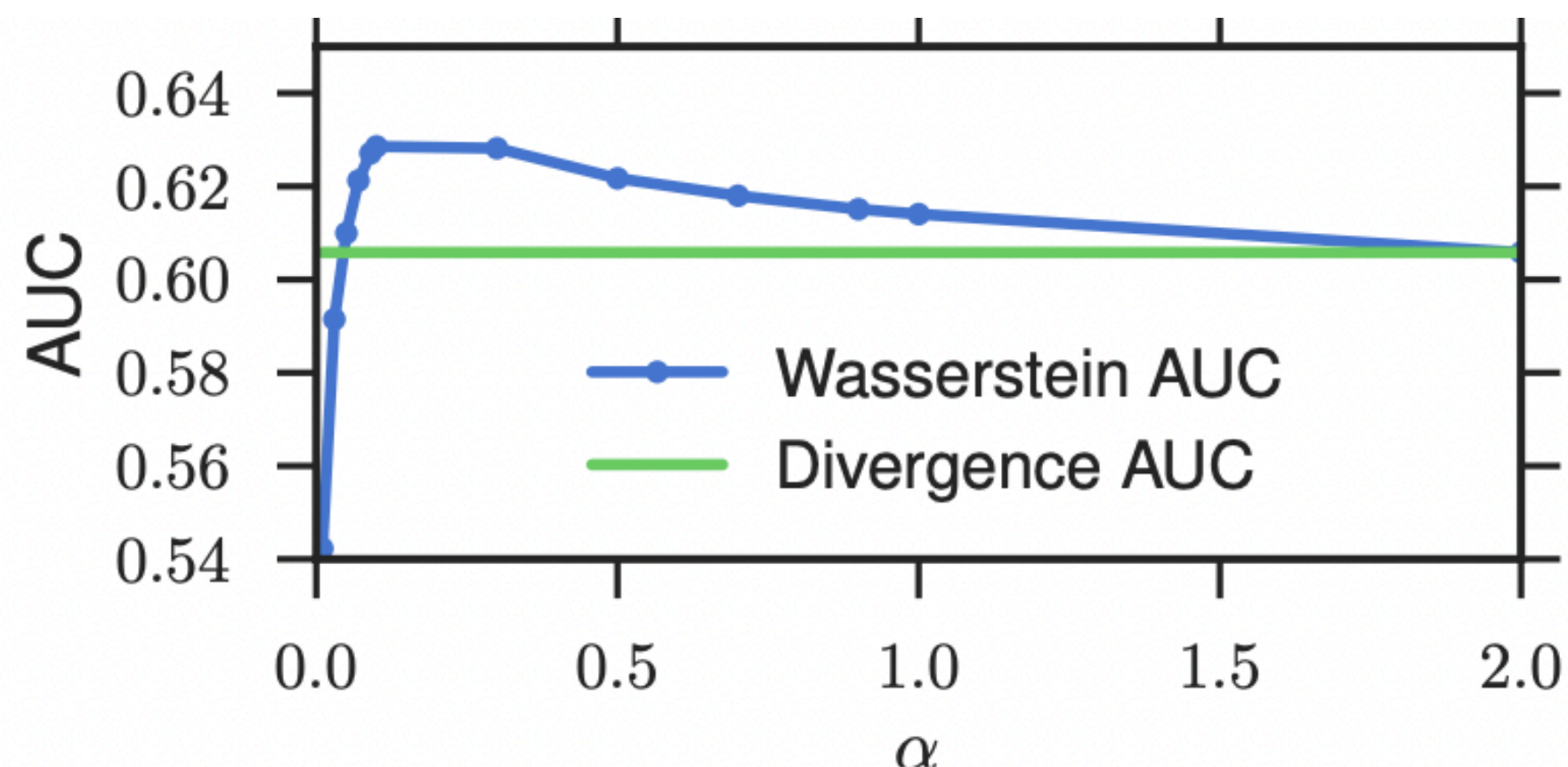


Image credit: [Frogner et al 2015]



Siberian husky



Eskimo dog

Image credit: [Frogner et al 2015]

# OT for Generative Modelling - WGAN

- Let  $\mathbb{P}_r$  denote the real data distribution over a metric space  $\Omega$  (i.e image space of  $[0,1]^{h \times w \times 3}$ ),
- Let  $Z$  be a random variable over a space  $\mathcal{Z}$ ,  $g : \mathcal{Z} \times \mathbb{R}^d \rightarrow \Omega$  a function parametrised by  $\theta \in \mathbb{R}^d$
- Let  $\mathbb{P}_\theta$  denote the distribution over  $g_\theta(Z)$
- [Arjovsky et al., 2017] trains generative models by minimising the  $W_1$  distance b/w  $\mathbb{P}_r$  and  $\mathbb{P}_\theta$

$$W_1^1(\mathbb{P}_r, \mathbb{P}_\theta) = \inf_{\gamma \in \mathcal{P}(\mathbb{P}_r, \mathbb{P}_\theta)} \mathbb{E}_{(x,y) \sim \gamma} [\|x - y\|]$$

- Using the semi-dual formulation, where  $f$  is a 1-Lipschitz function -

$$W_1^1(\mathbb{P}_r, \mathbb{P}_\theta) = \sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)]$$

- If instead we consider  $K$ -Lipschitz functions instead, we get

$$\sup_{\|f\|_L \leq 1} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)] \leq \sup_{\|f\|_L \leq K} \mathbb{E}_{x \sim \mathbb{P}_r} [f(x)] - \mathbb{E}_{x \sim \mathbb{P}_\theta} [f(x)] = K \cdot W_1^1(\mathbb{P}_r, \mathbb{P}_\theta)$$

# OT for Generative Modelling - WGAN

- Therefore, for parametrised family of functions  $\{f_\phi\}_{\phi \in \Phi}$  that are all K-Lipschitz, solve instead

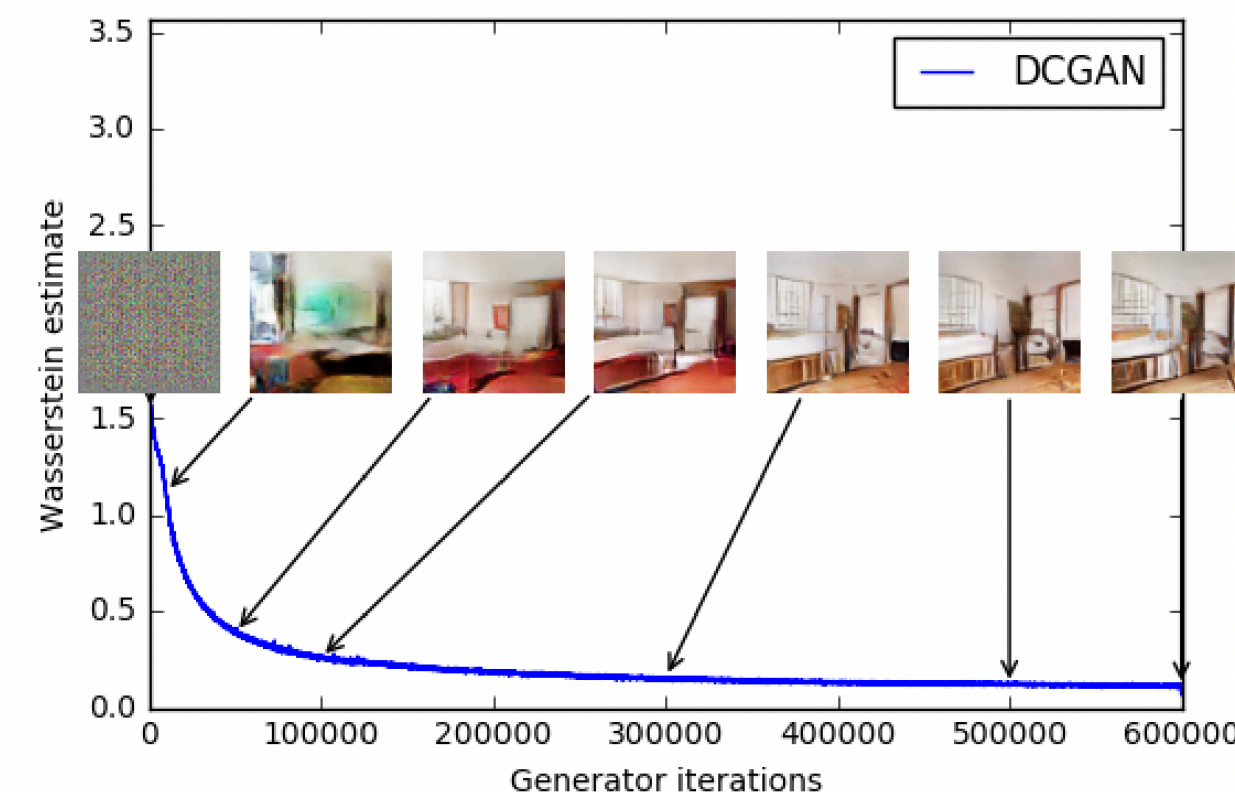
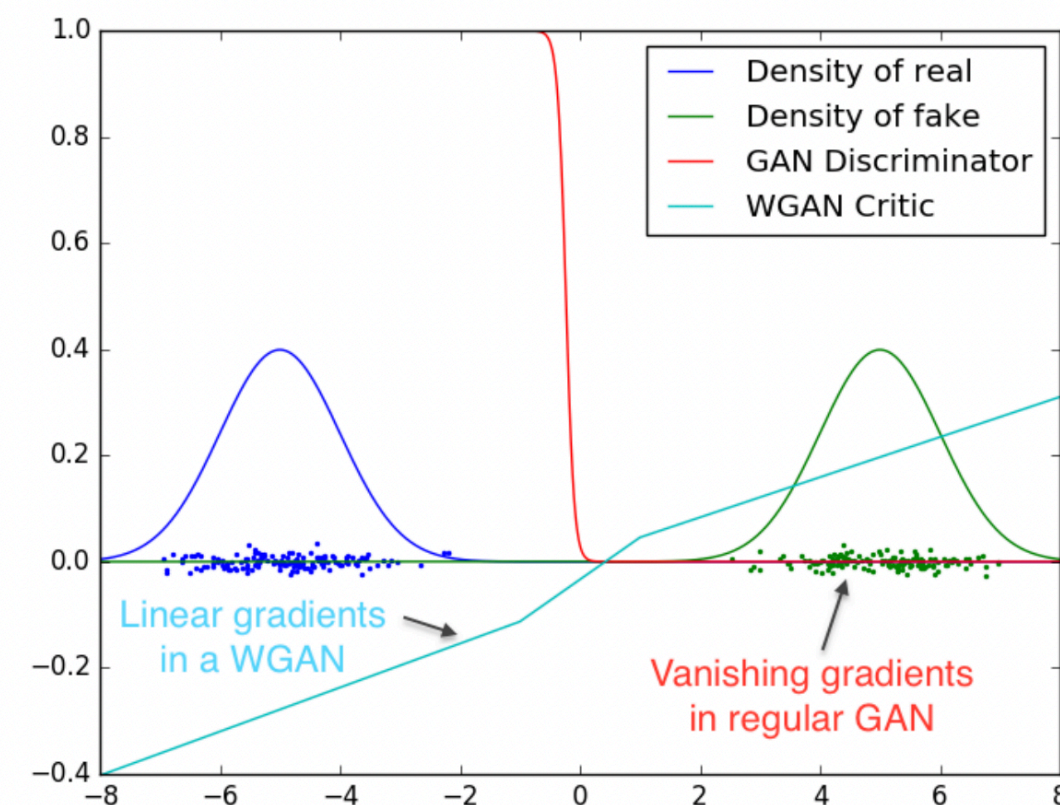
$$W(\mathbb{P}_r, \mathbb{P}_\theta) = \max_{\phi \in \Phi} \mathbb{E}_{x \sim \mathbb{P}_r} [f_\phi(x)] - \mathbb{E}_{z \sim p(z)} [f_\phi(g_\theta(z))]$$

- The paper proves that  $W(\mathbb{P}_r, \mathbb{P}_\theta)$  is the  $W_1$  distance unto a multiplicative factor, and further that

$$\nabla_\theta W(\mathbb{P}_r, \mathbb{P}_\theta) = - \mathbb{E}_{z \sim p(z)} [\nabla_\theta f(g_\theta(z))]$$

- K-Lipschitz bound is roughly enforced by gradient clipping

$$\phi \leftarrow \text{clip}(\phi, -c, c)$$



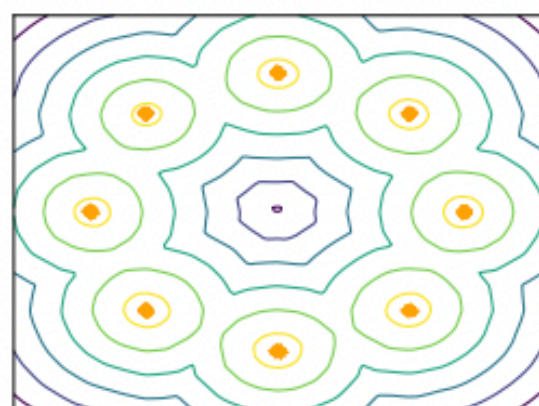
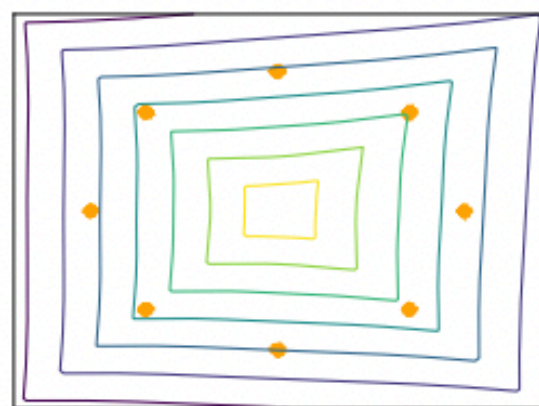
# OT for Generative Modelling - Extensions

- [Guljarani et al., 2017] Improved WGAN - Replace weight clipping with constraint on gradient norm

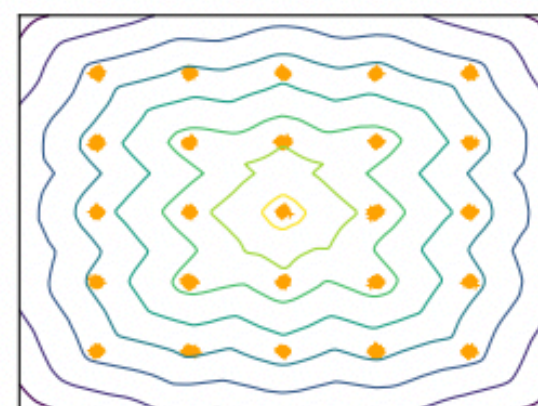
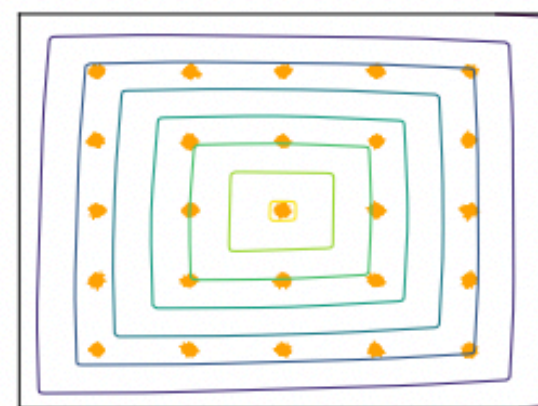
- $$W(\mathbb{P}_r, \mathbb{P}_\theta) = \max_{\phi \in \Phi} \mathbb{E}_{x \sim \mathbb{P}_r} [f_\phi(x)] - \mathbb{E}_{z \sim p(z)} [f_\phi(g_\theta(z))] + \lambda \mathbb{E}_{x \sim \mathbb{P}_r} \left[ \left( \|\nabla f_\phi(\mathbf{x})\|_2 - 1 \right)^2 \right]$$

- A differentiable function is 1-Lipschitz i.f.f it has gradients with norm at most 1 everywhere

8 Gaussians



25 Gaussians



Swiss Roll

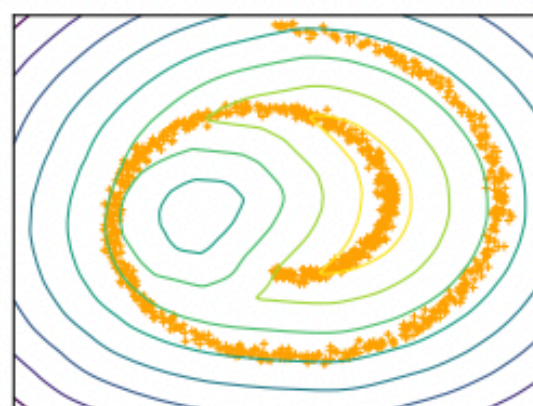
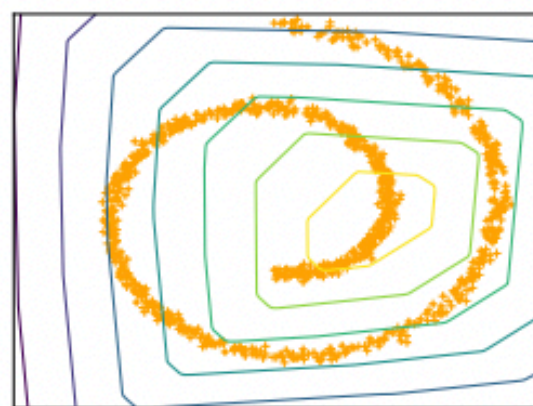


Image credit:[Guljarani et al 2017]

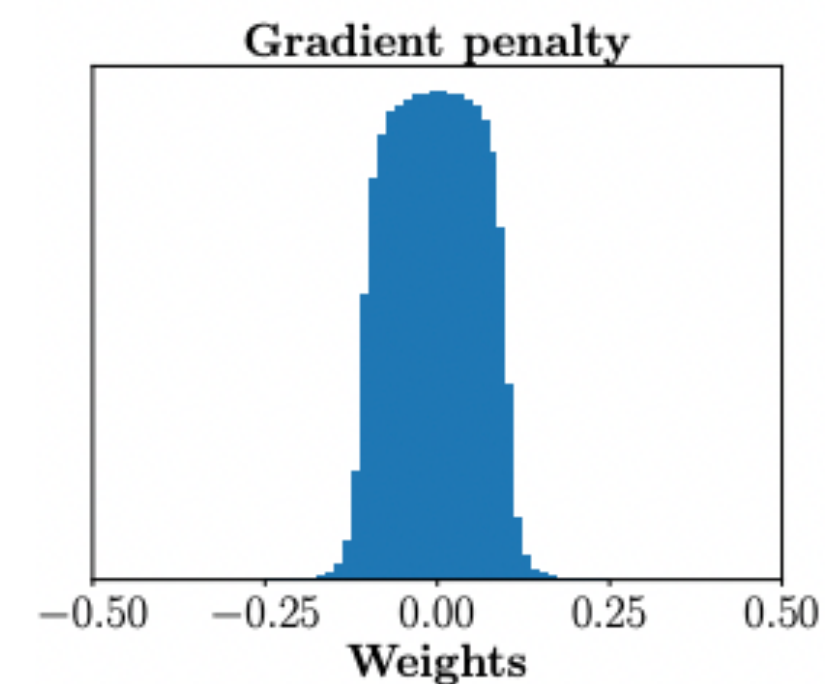
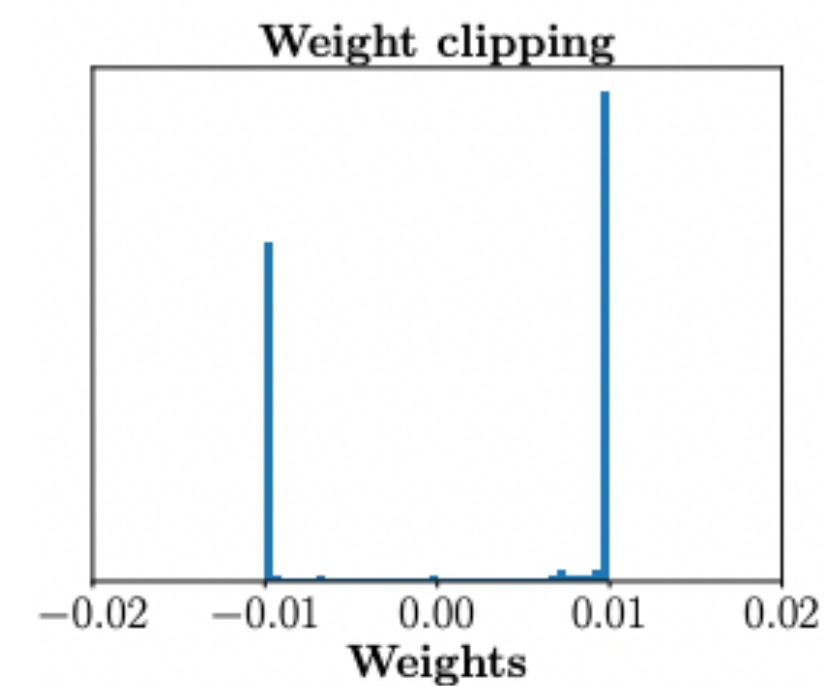


Image credit:[Guljarani et al 2017]



# OT for Generative Modelling - Sinkhorn Divergences

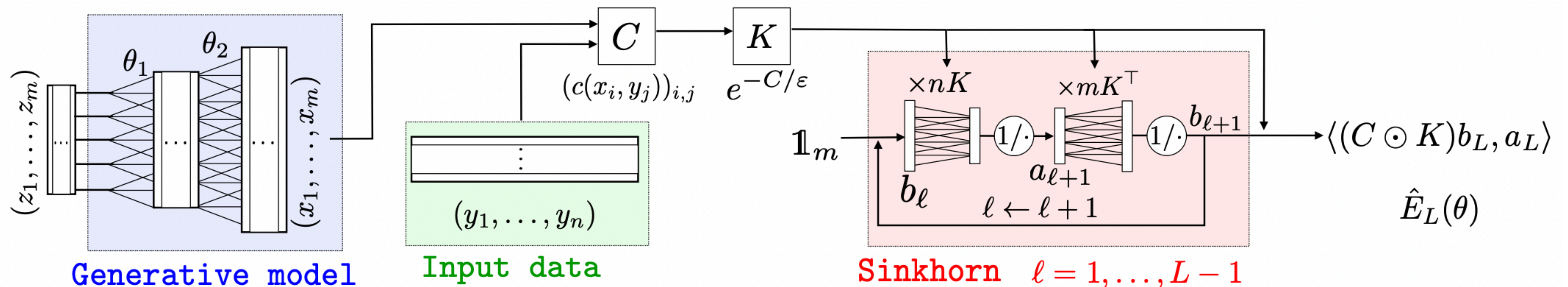
- [Genevay et al., 2017] Generative Models with Sinkhorn Divergences

- Define  $\mathbb{P}_r = \frac{1}{N} \sum_{j=1}^N \delta_{y_j}$  the empirical data distribution,  $\mathbb{P}_\theta = g_\theta(Z)$

- Generator is trained through  $\min_{\theta} \hat{E}_L(\theta) = \bar{W}_\lambda(\mathbb{P}_r, \mathbb{P}_\theta) \simeq 2W_L(\mathbb{P}_r, \mathbb{P}_\theta) - W_L(\mathbb{P}_r, \mathbb{P}_r) - W_L(\mathbb{P}_\theta, \mathbb{P}_\theta)$

- Cost function in general is  $c_\phi(x, y) = \|f_\phi(x) - f_\phi(y)\|$  where  $f_\phi : \mathcal{X} \rightarrow \mathbb{R}^p$

- $\frac{\partial W_L}{\partial \theta}, \frac{\partial W_L}{\partial \phi}$  can be obtained through autodiff



# Extensions to OT

# Unbalanced Optimal Transport

- $(\mu(\Omega_s) = \nu(\Omega_t))$  no longer holds true?
- Modify the OT problem into a variational formulation - adding infinite sources/sinks, mass creation
- [Matthias et al 2016] Given two measures  $\mu \in M_+(\Omega_s), \nu \in M_+(\Omega_t)$ ,

- Choose  $0 < m \leq \min\{\mu(\Omega_s), \nu(\Omega_t)\}$

- Define  $\gamma_t = \int_{\Omega_t} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{y}, \gamma_s = \int_{\Omega_s} \gamma(\mathbf{x}, \mathbf{y}) d\mathbf{x}$  and solve

$$\min_{\gamma \in \mathcal{M}_+(\Omega_s \times \Omega_t)} \int c(x, y) d\gamma(x, y) \quad \text{subject to } \gamma_t \leq \mu, \gamma_s \leq \nu, \gamma(\Omega_s \times \Omega_t) = m$$

- Generalise the Wasserstein distance to this setting with the **Wasserstein Fisher-Rao distance**

$$\widehat{W}_2^2(\mu, \nu) = \min_{\gamma \in M_+(\Omega_s \times \Omega_t)} KL(\gamma_t | \mu) + KL(\gamma_s | \nu) + \int c_\ell(x, y) d\gamma(x, y)$$

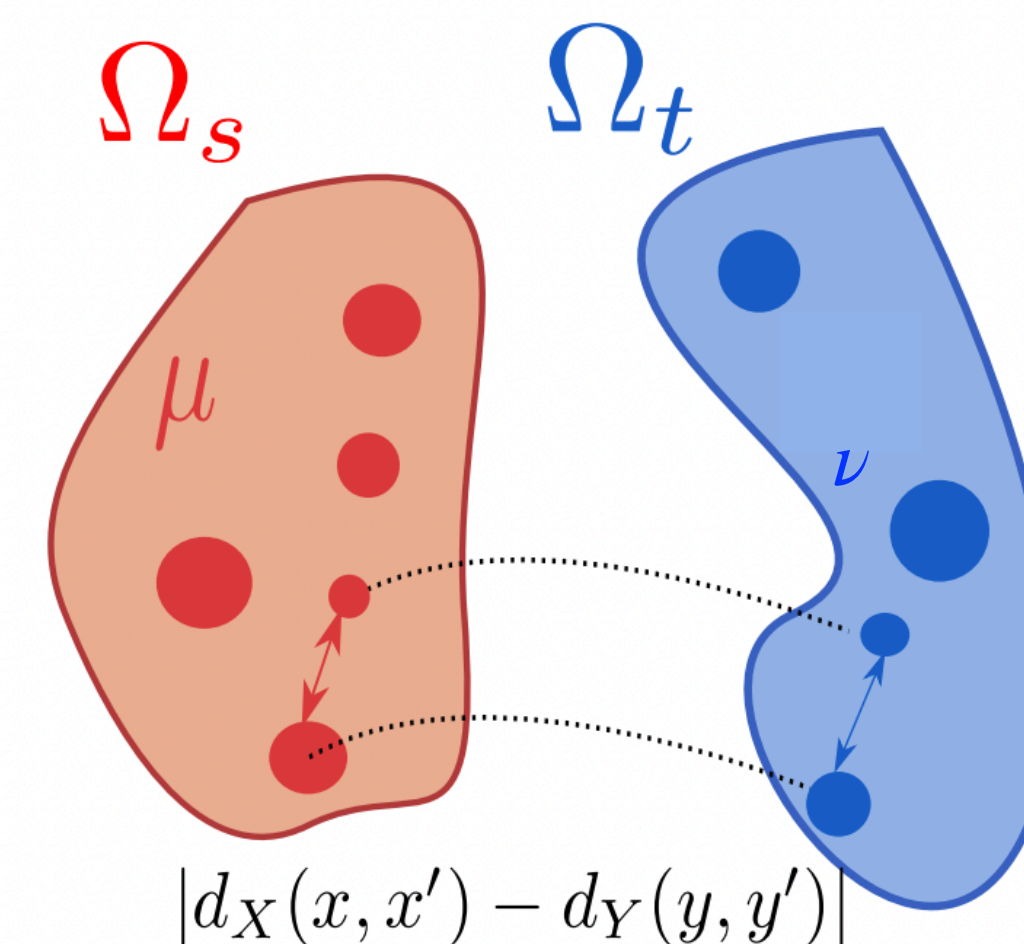
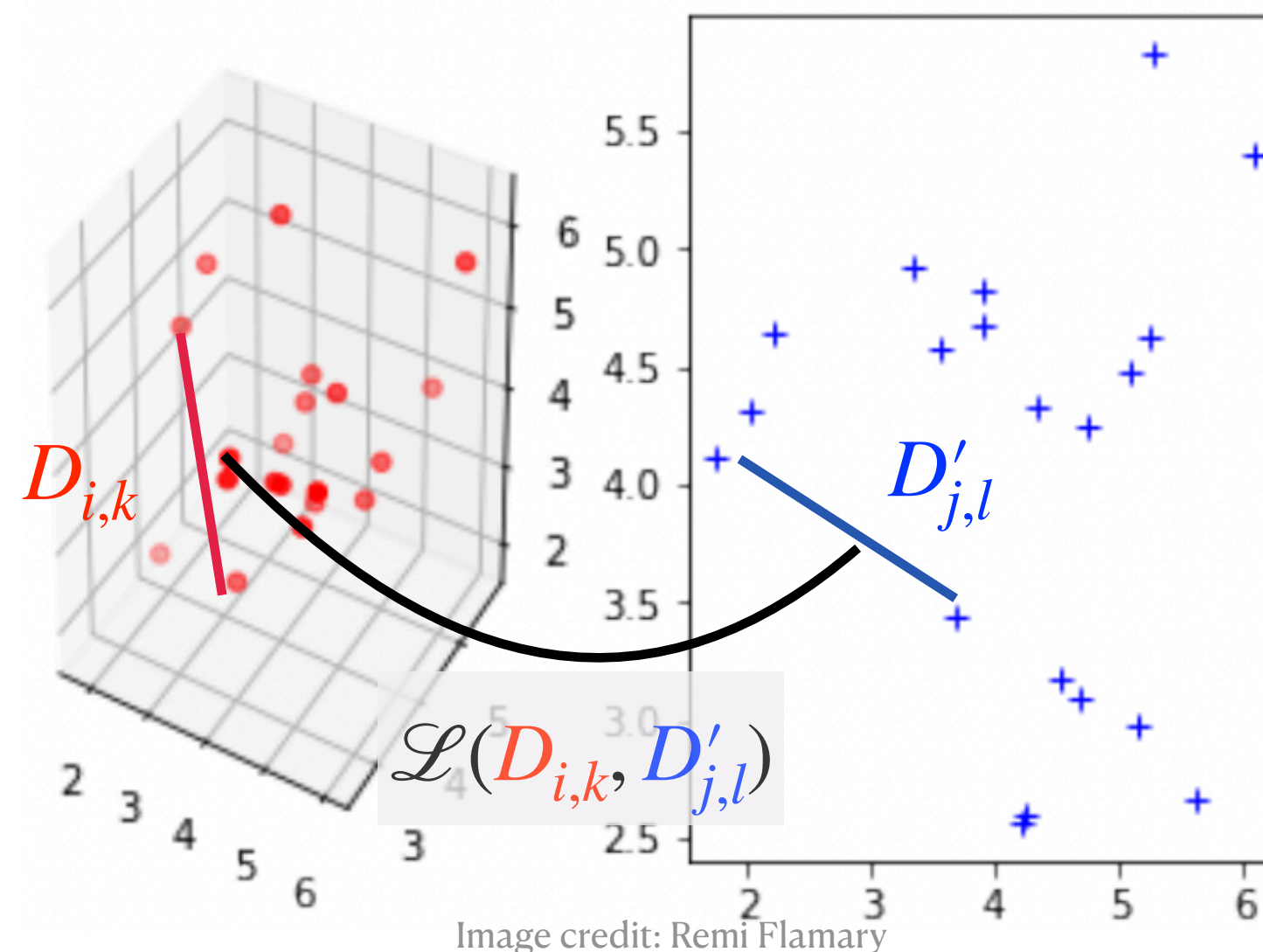
- [Peyre et al., 2017] General algorithm using entropic regularised WFR with Sinkhorn iterations

# OT between different metric spaces

- Can you perform OT between two spaces without  $c(x, y)$  or when  $\dim(\Omega_s) \neq \dim(\Omega_t)$ ?
- Extending OT metrics to measures with no common ground space
- [Memoli, 2011] proposed Gromov-Wasserstein distance

$$\mathcal{GW}_p(\mu, \nu) = \left( \min_{\gamma \in \mathcal{P}(\mu, \nu)} \mathcal{L}(D_{i,k}, D'_{j,l}) \times \gamma_{i,j} \times \gamma_{k,l} \right)^{\frac{1}{p}}$$

with  $D_{i,k} = \|\mathbf{x}_i^s - \mathbf{x}_k^s\|$ ,  $D'_{j,l} = \|\mathbf{x}_j^t - \mathbf{x}_l^t\|$ ,  $\mathcal{L}(D_{i,k}, D'_{j,l})$  is a dissimilarity metric b/w distances



# OT between different metric spaces

- This is a Quadratic Program - Nonconvex, NP-hard
- [Peyre et al., 2016] proposed an entropic regularisation relaxation of this problem

$$\mathcal{GW}_\lambda(\mu, \nu) = \left( \min_{\gamma \in \mathcal{P}(\mu, \nu)} \mathcal{L}(D_{i,k}, D'_{j,l}) \times \gamma_{i,j} \times \gamma_{k,l} \right) - \lambda \mathbb{H}(\gamma)$$

- This regularised term can be solved using projected gradient descent/Sinkhorn's algorithm

$$\gamma^{k+1} \leftarrow \operatorname{argmin}_{\gamma^k \in \mathcal{P}} \left\langle \gamma, \mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k \right\rangle - \lambda H(\gamma)$$

- Where  $\mathbf{K}' = \mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k$ , the tensor product where  $\mathcal{L}(D_{i,k}, D'_{j,l}) \otimes \gamma^k = \left( \mathcal{L}(D_{i,k}, D'_{j,l}) \gamma_{k,l} \right)_{i,j}$
- Sinkhorn's algorithm returns a stationary point of the nonconvex optimisation problem

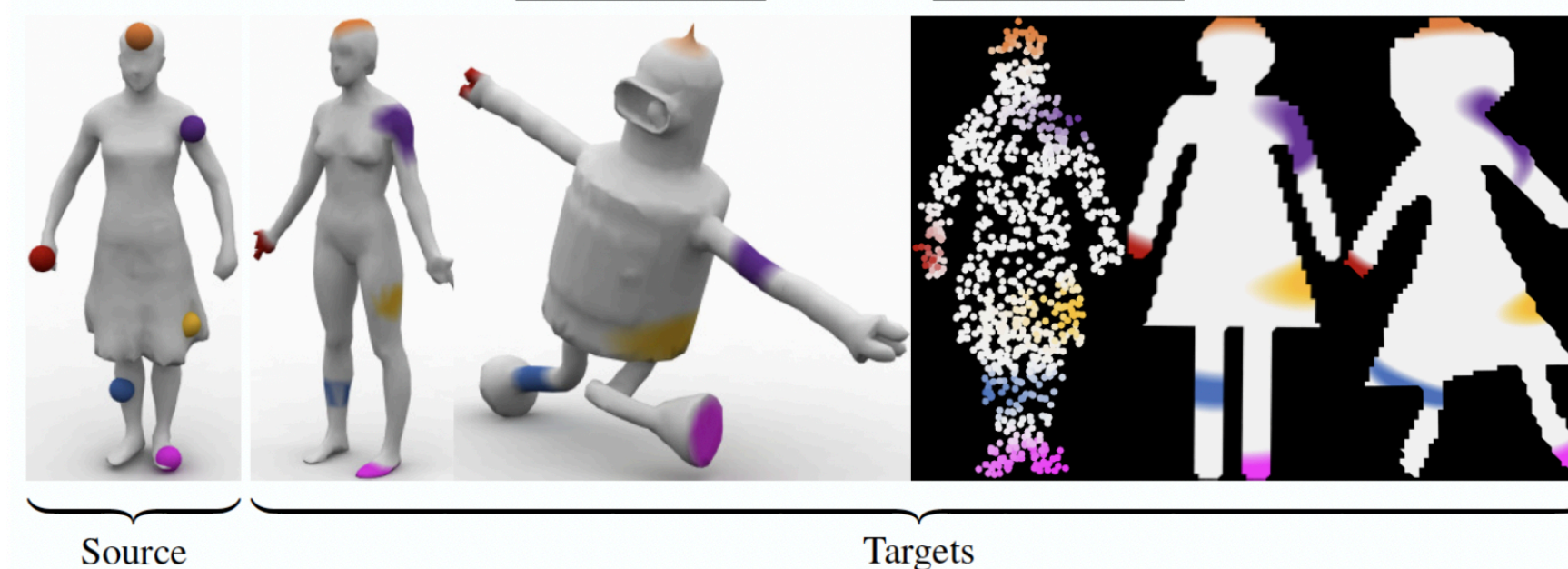


Image credit: [Peyre et al 2016]

# Conclusions

- Optimal Transport Theory provides a rigorous and rich mathematical formulation for defining metrics/discrepancy measures between probability measures
- In practise, cheap and efficient approximations have been developed recently
- Applications in generative modelling, supervised learning, computer vision and graphics
- Other cool research to read about
  - [Blanchet et al., 2021] Distributionally Robust Optimisation
  - [Durmus et. Al, 2019] Convergence of Langevin Dynamics Monte Carlo in Wasserstein geometry
  - [Kolouri et al., 2020] Optimal Transport on graphs and arbitrary manifolds through Wasserstein embeddings
  - [Courty et al., 2015] Domain Adaptation with Optimal Transport
  - [Craig et al., 2017] Wasserstein Gradient Flows

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